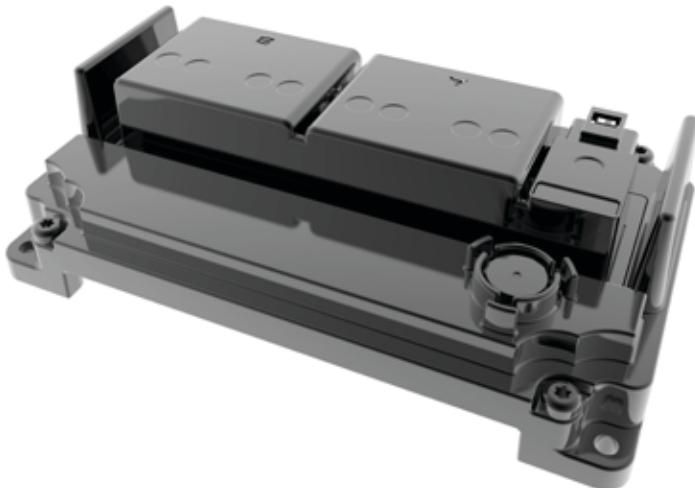


## Programmed with Eaton Pro-FX® control software

32-bit processor, 48 I/O (24 inputs & 24 outputs), 3 CAN interfaces  
supply voltage 6-32 VDC

The high-performance HFX48m control unit is designed for electronic control of all system functions on and off-highway mobile equipment. This control unit features a powerful processor, configurable CAN channels and a flexible I/O system to meet the needs of a variety of demanding applications.



### Technical data

<b>Dimensions</b>	L: 5.3 in (134.2 mm) x W: 8.4 in (212.6 mm) x H: 2.3 in (58.6 mm)
<b>Weight</b>	2.69 lbs (1.22 kg)
<b>Storage temperature range</b>	-40 - +125°C
<b>Operating temperature range</b>	-40 - +105°C (USB use is limited to 85°C)
<b>IP rating</b>	IP67, IP69k
<b>Operating altitude</b>	0 - 4000 m
<b>Supply voltage</b>	6 - 32 VDC, nominal operation @ 12/24 VDC
Peak supply voltage	36 VDC
Maximum load current	40A @ 105°C (48A @ 85°C)
Standby current 12/24 VDC	<3.5 mA@12 V, <2.5 mA@24 V
<b>Processor</b>	32 bit, 200 MHz, Renesas Super H 72546
Floating point units	Integrated on chip
<b>MRAM</b> (additional to CPU)	32 Kbyte approx. 1 trillion writes
<b>Flash</b> (ROM program & data combined)	3.75 Mbyte 1000 writes
<b>SRAM</b>	256 Kbyte
<b>EEPROM</b>	128 Kbyte (system use only)

# Technical data

## **Communications**

<b>CAN 1 interface</b>	2.0A, 2.0B
<b>Baud rates</b>	125 kb/s, 250 kb/s, 500 kb/s, 1Mb/s
<b>Protocol</b>	CANopen, J1939
<b>Default node address</b>	0
<b>Default baud rate</b>	250 kb/s
 <b>CAN 2 interface</b>	 2.0A, 2.0B
<b>Baud rates</b>	125 kb/s, 250 kb/s, 500 kb/s, 1 Mb/s
<b>Protocol</b>	CANopen, J1939
 <b>CAN 3 interface</b>	 2.0A, 2.0B
<b>Baud rates</b>	125 kb/s, 250 kb/s, 500 kb/s, 1 Mb/s
<b>Protocol</b>	CANopen, J1939
 <b>USB interface</b>	 USB 2.0 (Note: 3.0 devices are compatible), used for programming
<b>Baud rates</b>	1.5 Mb/s

## **Sensor supply**

<b>Number of sensor supplies</b>	2
<b>Sensor supply output voltage</b>	5/10 VDC (software configurable)
<b>Sensor supply maximum current</b>	200 mA @ 5 VDC, 100 mA @ 10 VDC per supply (Note: sensor supply is de-rated to 50 mA @ 10 VDC on 24 VDC systems with ambient temperatures at or above 85°C)

# Technical data

## Inputs

<b>Digital input</b>	Digital low/high side (software configurable)
<b>Input frequency</b>	200 Hz
<b>Switch-on level</b>	Software configurable
<b>Switch-off level</b>	Software configurable
 <b>Frequency input</b>	Digital low/high side (software configurable)
<b>Input frequency</b>	0 Hz - 50 kHz Note: maximum aggregate is 200 kHz, minimum detectable pulse duration is 20 $\mu$ sec
 <b>Frequency input</b>	Variable reluctance (software configurable)
<b>Input frequency</b>	0 Hz - 25 kHz Note: maximum aggregate is 200 kHz, minimum detectable pulse duration is 20 $\mu$ sec
<b>Switch-on level</b>	Selectable as 2.2 V or Adaptive
<b>Switch-off level</b>	Selectable as 0.0 V or 1.0 V
 <b>Analog input</b>	0 - 5 V (absolute & ratiometric), 0 - 10 V, 0 - 32 V , 0 - 20 mA, thermistor (software configurable)
<b>Resolution</b>	12 bits
<b>Accuracy</b>	+/- 0.2 % FS (0-5 VDC mode), +/- 1 % FS (all other modes)
<b>Short circuit protection</b>	Integrated
 <b>Voltage input</b>	0 - 5 V
<b>Input frequency</b>	1 kHz
 <b>Voltage input</b>	0 - 10 V
<b>Input frequency</b>	1 kHz
 <b>Voltage input</b>	0 - 32 V
<b>Input frequency</b>	1 kHz
 <b>Thermistor input</b>	
<b>Input resistance</b>	22 kOhm pull-up
<b>Sample frequency</b>	1 kHz
<b>Accuracy</b>	+/-1%
<b>Current input</b>	0 - 20 mA
<b>Input resistance</b>	
<b>Input frequency</b>	1 kHz

# Technical data

## Outputs

<b>Digital output – 2A</b>	High side
<b>Max amperage</b>	2A
<b>Diagnostics</b>	Open/short circuit protection
<b>PWM output current feedback – 2A</b>	High side (software configurable)
<b>Max Amperage</b>	2A
<b>Diagnostics</b>	Open/short circuit protection
<b>PWM frequency</b>	.05 Hz – 2 kHz or 50 Hz – 2 kHz
<b>Dither frequency</b>	Configurable
<b>Dither amplitude</b>	Configurable
<b>Control range</b>	0.05 - 2A
<b>Control resolution</b>	1 mA
<b>Fly back protection</b>	Integrated
<b>Duty cycle resolution</b>	.01% @ 250 Hz
<b>Digital output – 4A</b>	Low/high side, H-bridge (software configurable)
<b>Max amperage</b>	4A
<b>Diagnostics</b>	Open/short circuit protection
<b>PWM output current feedback – 4A</b>	Low/high side, H-bridge (software configurable) in PWM mode, high side (software configurable) in current control mode
<b>Max amperage</b>	4A
<b>Diagnostics</b>	Open/short circuit protection
<b>PWM frequency</b>	50 - 500 Hz
<b>Dither frequency</b>	Configurable
<b>Dither amplitude</b>	Configurable
<b>Control range</b>	0.05 - 4A
<b>Control resolution</b>	1.5 mA
<b>Fly back protection</b>	Integrated
<b>Duty cycle resolution</b>	.01% @ 250 Hz

## Connections

<b>Connector – 6 Pin</b>	Deutsch Inc.
<b>Model</b>	DT04-6P
<b>Contact surface</b>	Nickel plated
<b>Connector – 40 Pin</b>	Deutsch Inc.
<b>Model</b>	DRC23-40PA, DRC23-40PB
<b>Contact surface</b>	Nickel plated
<b>Torque specification</b>	25-28 in-lbs (2.82 - 3.16 N-m)

# Technical data

## Standards

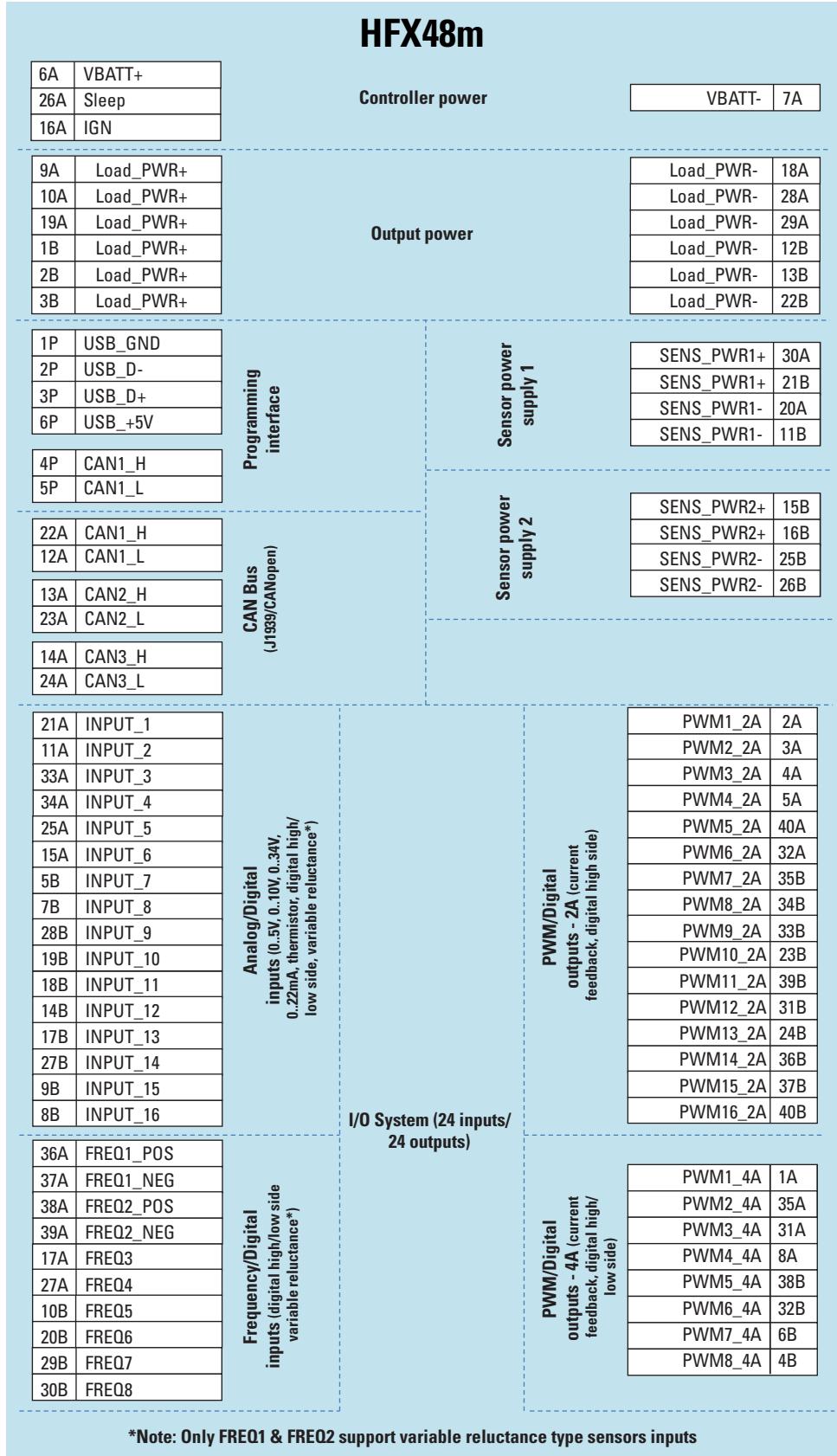
<b>Temperature environment</b>	SAE J1455
<b>Environmental</b>	SAE J1455
<b>Salt spray</b>	J1455 Section 4.3.3
<b>Vibration</b>	J1455 Section 4.10.4.1
<b>Drop</b>	J1455 Section 4.11.3.1
<b>Shock</b>	J1455 Section 4.10.4
<b>Conducted immunity</b>	SAE J1113, EN 61326-1, 2004/108/EC
<b>Radiated immunity</b>	SAE J1113, EN 61326-1, 2004/108/EC
<b>Conducted emissions</b>	CISPR 25, EN 60945, 2004/108/EC
<b>Radiated emission</b>	CISPR 25, CISPR 11, EN60945

## Certifications

**CE Mark**

**e-Mark**

# Block diagram



# Pin list

## Communications connector

Type	Deutsch	DT04-6P
Pin	Function	
1	Ground	
2	USB data low	
3	USB data high	
4	CAN 1 high	
5	CAN 1 low	
6	USB power 5V	

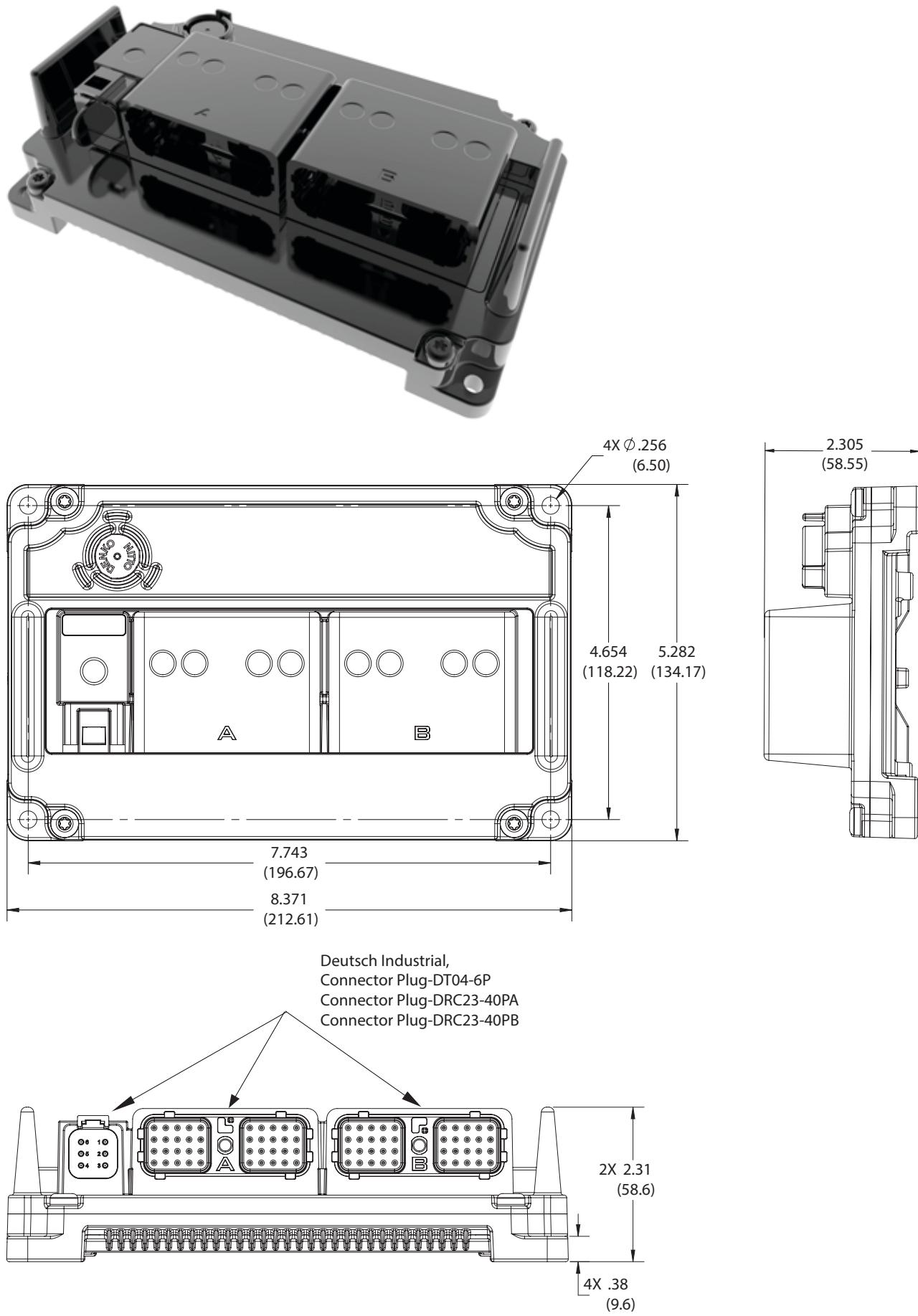
## Connector A

Type	Deutsch	DRC23-40PA
Pin	Function	
1	Output PWM1 4A	
2	Output PWM1 2A	
3	Output PWM2 2A	
4	Output PWM3 2A	
5	Output PWM4 2A	
6	System power positive	
7	System power negative	
8	Output PWM4 4A	
9	Load power positive	
10	Load power positive	
11	Input 2	
12	CAN 1 low	
13	CAN 2 high	
14	CAN 3 high	
15	Input 6	
16	Ignition	
17	Frequency 3	
18	Load power negative	
19	Load power positive	
20	Sensor power 1 negative	
21	Input 1	
22	CAN 1 high	
23	CAN 2 low	
24	CAN 3 low	
25	Input 5	
26	Sleep	
27	Frequency 4	
28	Load power negative	
29	Load power negative	
30	Sensor power 1 positive	
31	Output PWM3 4A	
32	Output PWM6 2A	
33	Input 3	
34	Input 4	
35	Output PWM2 4A	
36	Input frequency 1 positive	
37	Input frequency 1 negative	
38	Input frequency 2 positive	
39	Input frequency 2 negative	
40	Output PWM5 2A	

## Connector B

Type	Deutsch	DRC23-40PB
Pin	Function	
1	Load power positive	
2	Load power positive	
3	Load power positive	
4	Output PWM8 4A	
5	Input 7	
6	Output PWM7 4A	
7	Input 8	
8	Input 16	
9	Input 15	
10	Frequency 5	
11	Sensor power 1 negative	
12	Load power negative	
13	Load power negative	
14	Input 12	
15	Sensor power 2 positive	
16	Sensor power 2 positive	
17	Input 13	
18	Input 11	
19	Input 10	
20	Frequency 6	
21	Sensor power 1 positive	
22	Load power negative	
23	Output PWM10 2A	
24	Output PWM13 2A	
25	Sensor power 2 negative	
26	Sensor power 2 negative	
27	Input 14	
28	Input 9	
29	Frequency 7	
30	Frequency 8	
31	Output PWM12 2A	
32	Output PWM6 4A	
33	Output PWM9 2A	
34	Output PWM8 2A	
35	Output PWM7 2A	
36	Output PWM14 2A	
37	Output PWM15 2A	
38	Output PWM5 4A	
39	Output PWM11 2A	
40	Output PWM16 2A	

# Mounting diagram



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