

# EFX IO84 Input/Output Module

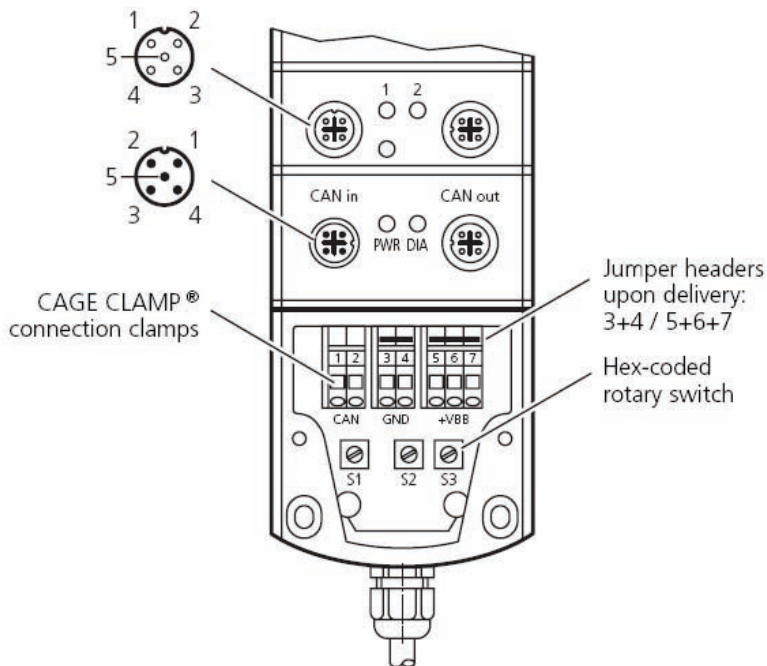
Input/Output expansion module for EFX Controllers  
 CANopen interface  
 Surface electrostatically coated (cathodic immersion) 10...32V DC

Technical Data	8 Inputs (4 Digital / 4 Analog) 4 Outputs (Digital or PWM)
<b>Housing</b>	Die-cast zinc housing with 8 outputs and terminal chamber surface electrostatically coated (cathodic immersion), black
<b>Dimensions (l x w x h)</b>	227 x 77 x 39 mm (without cable gland)
<b>Installation</b>	Screw connection by means of 3 M5 x l screws to DIN 912 or DIN 7984
<b>Connection</b> Operating voltage and CAN bus	7-pole terminal strip with CAGE CLAMP® connection technology (2 x 2-pole / 1 x 3-pole) 0.08...4 mm <sup>2</sup> (AWG 28...AWG 12), nominal current 20 A Identical potentials can be linked using a jumper header (GND and UB potentials linked upon delivery) Cable entry via M16 cable gland
Inputs/Outputs CANin/CANout	8 x M12 connector (socket), 5-pole 2 x M12 connector (plug/socket), 5-pole
<b>Weight</b>	1.2 kg
<b>Inputs</b> can be configured as	8 4 digital, positive-switching (high side) 4 analogue, 0...10/32 V, 0/4...20 mA, ratiometric or digital, positive-switching
<b>Sensor supply I<sub>max</sub></b>	400 mA
<b>Outputs</b> can be configured as switching current per output total current	4 digital, positive-switching (high side), with diagnostic capability PWM channel max. 4 A max. 16 A
<b>Operating voltage U<sub>B</sub></b>	10...32 V DC
<b>Current consumption</b>	≤ 50 mA (without external load at 24 V DC)
<b>Operating temperature</b>	– 40...85°C
<b>Storage temperature</b>	– 40...85 °C
<b>Protection</b>	IP-67
<b>Interface</b>	CAN interface 2.0 B, ISO 11898
<b>Baud rate</b>	20 Kbits/s...1 Mbit/s (default setting 125 Kbits/s) (adjustable using hex-code switches in the terminal chamber or via the CANopen object directory)
<b>Communication profile</b>	CANopen, CiA DS 301 version 4, CiA DS 401 version 2.1
<b>Node ID</b> (default)	hex 20 (= dec 32) (adjustable using 2 hex-code switches in the terminal chamber or via the CANopen object directory)
<b>Displays</b>	1 LED green (PWR) 1 LED red (diagnosis, DIA) 8 LEDs yellow (status of the inputs / outputs)



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Connecting and operating elements



Hex-code switch coding

Switch	Position	Description
S1 Baud rate	0	1000 Kbits/s
	1	800 Kbits/s
	2	500 Kbits/s
	3	250 Kbits/s
	4	125 Kbits/s
	5	100 Kbits/s
	6	50 Kbits/s
	7	20 Kbits/s
	8...E	not defined
	F	adjustment via object directory (default)
S2	0...7	high nibble, e.g. 20 hex (= 32 dec)
Node ID <sub>H</sub>	F	adjustment via object directory (default)
S3	0...E	low nibble, e.g. 20 hex (= 32 dec)
Node ID <sub>L</sub>	F	adjustment via object directory (default)



Operating states (LEDs)

LED	Status	Description
PWR (green)	OFF	no supply voltage
	ON	module in stand-by mode
		CANopen status: PREOPERATIONAL/PREPARED
	2.0 Hz	outputs = OFF module active CANopen status: OPERATIONAL outputs are updated
DIA (red)	OFF	communication OK
	ON	communication disturbed <ul style="list-style-type: none"> <li>• node guard / heartbeat error (if node guarding / heartbeat is activated)</li> <li>• no synch objects (if synch monitoring is activated)</li> </ul>
IN (yellow)	ON	output switched
OUT (yellow)	ON	binary output: output switched (ON) analogue output: PWM preset value ≠ 0 current preset value > 20

**Inputs**

Channel 1, 3, 5, 7 (pin 4)

■ Digital inputs	
Switch-on level	0.4...0.7 UB
Switch-off level	0.2...0.24 UB
Input resistance	3 kΩ
Input frequency	max. 1 kHz

**Channel 1...8 (pin 2)**

can be configured as ...

- Analogue inputs (voltage, current or ratiometric)  
The analogue signals can be connected to the sockets 1, 3, 5, 7 or alternatively to the sockets 2, 4, 6, 8 (pin 2 of the sockets 1-2, 3-4, 5-6 and 7-8 linked).  
The LED (yellow) for the analogue input is on the socket side 1, 3, 5, 7.

Voltage inputs	
Input voltage	0...10/32 V
Resolution	10 bits
Input resistance	50/30 kΩ
Input frequency	50 Hz
Accuracy	± 1 % FS

Current inputs	
Input current	0/4...20 mA
Resolution	10 bits
Input resistance	400 Ω
Input frequency	50 Hz
Accuracy	± 1 % FS

Ratiometric inputs for potentiometric transducers (e.g. joystick)

Function	$((U_{IN} - \frac{1}{2}U_B) \div \frac{1}{2}U_B) \times 1000 \text{ ‰}$
Value range	0...1000 ‰

Digital inputs	Switch-on level	0.7 UB
	Switch-off level	0.4 UB
	Input resistance	30 kΩ
	Input frequency	max. 50 Hz

**Outputs**

Channel 2, 4, 6, 8 (pin 4)  
can be configured as ...

- Semiconductor outputs, with diagnostic capability (wire break and short circuit) Channel 2, 4, 6, 8 (pin 4) short-circuit and overload protected can be configured as ...

Switching voltage	10...32 V DC
Switching current	max. 4 A
Total current max.	16 A

■ PWM outputs	
PWM frequency	20...250 Hz
Pulse duty factor	0...1000 ‰
Resolution	1 ‰
Switching current	max. 4 A (referred to PWM value 1000 ‰.)
Total current	max. 16 A

**Note**

also see wiring (following page)

**Test standards and regulations**

**Climatic test**

Damp heat to EN 60068-2-30, test Db (≤ 95% rel. humidity, non-condensing), Salt mist test to EN 60068-2-52, test Kb, severity level 3, Protection test to EN 60529

**Mechanical resistance**

Vibration to EN 60068-2-6, test Fc, Shock to EN 60068-2-27, test Ea, Bump to EN 60068-2-29, test Eb

**Immunity to conducted interference**

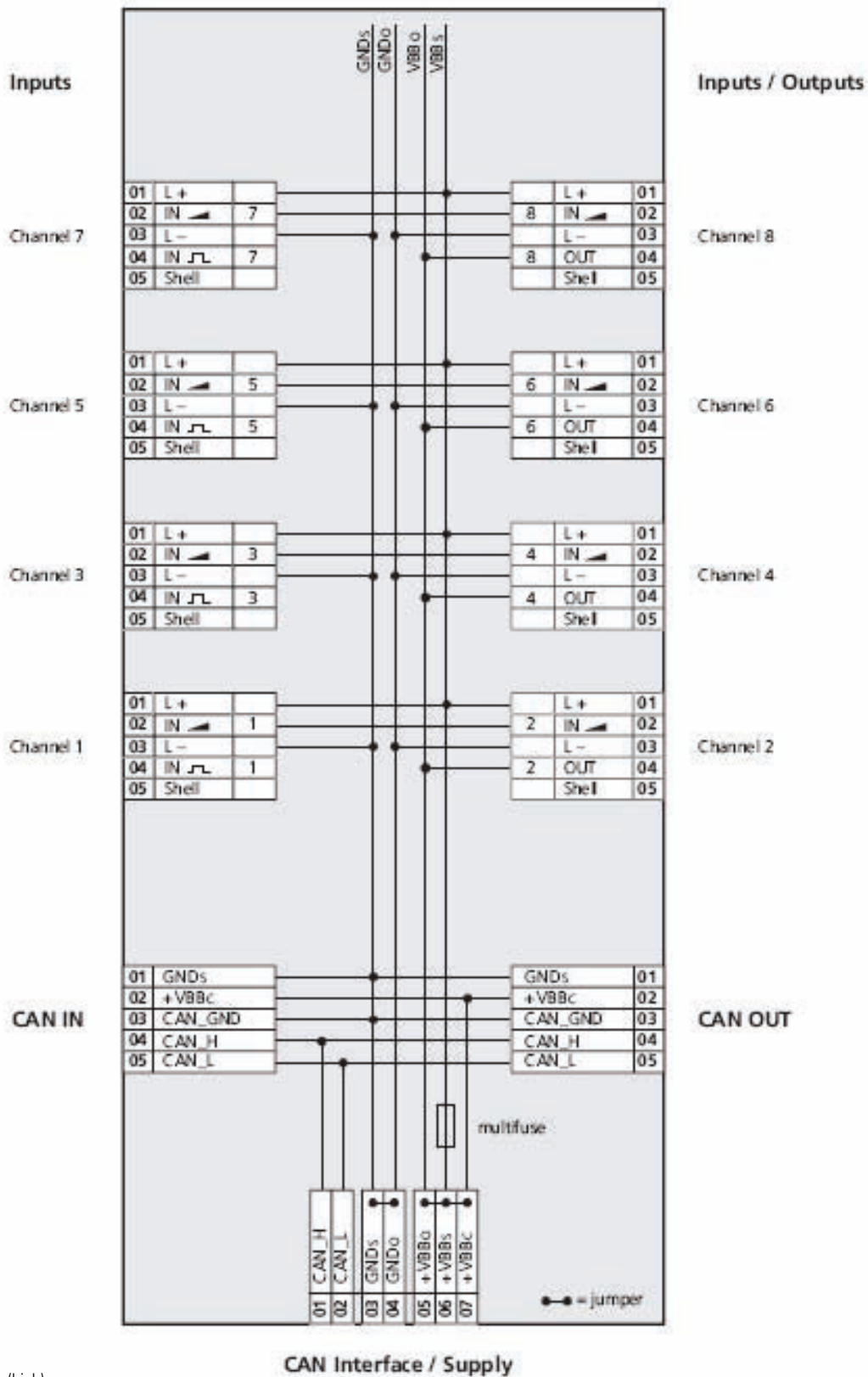
to ISO 7637-2, pulses 2, 3a, 3b, severity level 4, function state A  
to ISO 7637-2, pulse 5, severity level 1, function state A  
to ISO 7637-2, pulse 1, severity level 4, function state C

**Immunity to interfering fields**

directive 95/54/EC at 100 V/m (e1 type approval) and DIN EN 61000-6-2 :2001 (CE)

**Interference emission**

directive 95/54/EC (e1 type approval) and DIN EN 61000-6-4 :2001 (CE)



**Abbreviations:**

- CAN<sub>H</sub> = CAN interface (high)
- CAN<sub>L</sub> = CAN interface (low)
- GND<sub>o</sub> = ground (output)
- GND<sub>s</sub> = ground (module)
- PWM = output for pulse-width modulated signals
- VBB<sub>c</sub> = operating voltage (via CANin/CANout plug)
- VBB<sub>o</sub> = operating voltage (output)
- VBB<sub>s</sub> = operating voltage (module)

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