

Programmed with Eaton CONTROL F(x)™ Software to IEC 61131-3 Standard

2nd CAN interface for gateway function according to SAE J1939 Supply voltage 10...32V DC

Technical Data		Controller for the Implementation of a Central or Decentralized Electrohydraulic System			
Housing	closed screened metal housing with flange fastening				
Dimensions (H x W x D)	153 x 226 x 43 mm				
Mounting	screw connection by means of 4 M5xL screws according to DIN 7500 or DIN 7984 mounting position horizontal or vertical to the mounting wall				
Connection	55-pin connector, latched, protected against reverse polarity type AMP housing or Framatome AMP junior timer contacts, crimp connection 0.5/2.5 mm ²				
Weight	1.2 kg				
Housing/storage temperature	– 40...85° C (depending on the load) / – 40...85° C				
Protection	IP 67 (for inserted plug with individually sealed cores e.g. ECEFX16 12S)				
Input/output channels	max. 24 (total number available depends on wiring and configuration of the controller)				
Total					
Inputs	max. 24 (corr. to 0 outputs)				
Possible configurations	Number	Signal	Version		
	8	digital	for positive sensor signals, with diagnostic capability	B _L	
	or	analog	0...10/32 V DC, 0/4...20 mA or ratiometric	A	
	8	digital	for positive sensor signals	B _L	
	4	digital	for positive sensor signals, with diagnostic capability	B _L	
	or	frequency	max. 50 kHz	I _L	
	4	digital	for positive/negative sensor signals, with diagnostic capability*	B _{L/H}	
	or	frequency	max. 1 kHz	I _L	
			*only positive sensor signals with diagnostic capability		
Outputs					
Possible configurations	Number	Signal	Version		
	8	digital	positive switching (high side), with diagnostic capability	B _H	
			max. 8 (corr. to 16 inputs)		
	or	PWM	PWM frequency 20...250 Hz	PWM	
	or	current-controlled	f ₀ , 1...4 A	PWM _I	

Abbreviations

A	= analog
B _H	= binary high side
B _L	= binary low side
FRQ/CYL	= frequency inputs
I _H	= pulse high side
I _L	= pulse low side
PWM	= pulse width modulation
PWM _I	= current-controlled output
%IWx	= IEC address for analog input
%IX0.xx	= IEC address for binary input
%QX0.xx	= IEC address for binary output



Powering Business Worldwide

EFX 1624m	Technical Data		
Operating voltage U_B	10...32 V DC		
Overvoltage	36 V for t ≤ 10 s		
Undervoltage detection	for U _B ≤ 10 V		
Switching-off in case of undervoltage	for U _B ≤ 8 V		
Current consumption	≤ 160 mA (without external load at 24 V DC)		
CAN interface 1	CAN interface 2.0 B, ISO 11898		
Baud rate	50 Kbits/s...1 Mbits/s (default setting 125 Kbits/s)		
Communication profile	CANopen, CiA DS 301 version 4, CiA DS 401 version 1.4		
Node-ID (CANopen)	hex 7F (= dec. 127)		
CAN interface 2	CAN interface 2.0 A/B, ISO 11898		
Baud rate	50 Kbits/s...1 Mbits/s (default setting 125 Kbits/s)		
Communication profile	SAE J1939 or free protocol		
Serial interface	RS-232 C		
Baud rate	9.6 / 19.2 / 28.8 / 38.4 / 57.6 kBit/s (default setting 9.6 Kbits/s)		
Topology	point-to-point (max. 2 participants); master-slave connection		
Protocol	predefined protocol (INTELHEX)		
Processor	CMOS microcontroller 16 bits C167CS cycle frequency 20/40 MHz		
Device monitoring	undervoltage monitoring, watchdog function, check sum test for program, and system excess temperature monitoring		
Process monitoring concept	Two relays according to EN 954 monitor 2 groups of 4 outputs each		
Program memory	768 Kbytes Flash can be used by the user (+ 832 Kbytes for extended functions)		
Data memory	128 Kbytes SRAM, 128 Kbytes Flash		
Data memory (protected in case of power failure)	1024 bytes (retain data), 16 Kbytes (general data)		
Status indication	three-color LED (R/G/B)		
Operating status (status LED)	LED Color	Status	Description
	–	off	no operating voltage
	yellow	1 x on	initialization or reset checks
	green	5 Hz	no operating system loaded
	green	2.0 Hz	run
		on	stop
	red	2.0 Hz	run with error
		on	fatal error or stop with error
Test Standards and Regulations			
Climatic test	Damp heat to EN 60068-2-30, test Db (≤ 95% rel. humidity, non-condensing), salt mist test to EN 60068-2-52, test Kb, severity level 3 degrees of protection to EN 60529		
Mechanical resistance	Vibration to EN 60068-2-6, test Fc, shock to EN 60068-2-27, test Ea, bump to EN 60068-2-29, test Eb		
Immunity to conducted interference	to ISO 7637-2, pulses 2, 3a, 3b, severity level 4, function state A to ISO 7637-2, pulse 5, severity level 1, function state A to ISO 7637-2, pulse 1, severity level 4, function state C		
Immunity to interfering fields	directive 95/54/EC at 100 V/m (e1 type approval) and EN 61000-6-2 :2001 (CE)		
Interference emission	directive 95/54/EC (e1 type approval) and EN 61000-6-3 :2001 (CE)		
Tests for the approval for railway applications	to BN 411 002 (DIN EN 50155 clause 10.2)		

<p>Digital/analog inputs (B_L, A) %IW03...10 %IX0.00...07 Can be configured as ...</p>	<ul style="list-style-type: none"> ■ Voltage inputs <table border="0" style="width: 100%;"> <tr><td>input voltage</td><td>0...10/32 V</td></tr> <tr><td>resolution</td><td>12 bits</td></tr> <tr><td>precision</td><td>± 1.0% FS</td></tr> <tr><td>input resistance</td><td>50/30 kΩ</td></tr> <tr><td>input frequency</td><td>50 Hz</td></tr> </table> ■ Current inputs <table border="0" style="width: 100%;"> <tr><td>input current</td><td>0/4...20 mA</td></tr> <tr><td>resolution</td><td>12 bits</td></tr> <tr><td>precision</td><td>± 1.0% FS</td></tr> <tr><td>input resistance</td><td>400 Ω</td></tr> <tr><td>input frequency</td><td>50 Hz</td></tr> </table> ■ Digital inputs for positive sensor signals, with diagnostic capability * <table border="0" style="width: 100%;"> <tr><td>switch-on level</td><td>0.7 U_B</td></tr> <tr><td>switch-off level</td><td>0.4 U_B</td></tr> <tr><td>input resistance</td><td>30 kΩ</td></tr> <tr><td>input frequency</td><td>50 Hz</td></tr> </table> 	input voltage	0...10/32 V	resolution	12 bits	precision	± 1.0% FS	input resistance	50/30 kΩ	input frequency	50 Hz	input current	0/4...20 mA	resolution	12 bits	precision	± 1.0% FS	input resistance	400 Ω	input frequency	50 Hz	switch-on level	0.7 U _B	switch-off level	0.4 U _B	input resistance	30 kΩ	input frequency	50 Hz
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<p>Digital inputs (B_L, I_L) %IX0.12...15 Can be configured as ...</p>	<ul style="list-style-type: none"> ■ Digital inputs for positive sensor signals, with diagnostic capability * <table border="0" style="width: 100%;"> <tr><td>switch-on level</td><td>0.7 U_B</td></tr> <tr><td>switch-off level</td><td>0.4 U_B</td></tr> <tr><td>input resistance</td><td>2.86 kΩ</td></tr> <tr><td>input frequency</td><td>50 Hz</td></tr> </table> ■ Frequency inputs for positive sensor signals with diagnostic capability, evaluation with integrated comparator <table border="0" style="width: 100%;"> <tr><td>switch-on level</td><td>0.43...0.73 U_B</td></tr> <tr><td>switch-off level</td><td>0.29 U_B</td></tr> <tr><td>input resistance</td><td>2.86 kΩ</td></tr> <tr><td>input frequency max.</td><td>50 kHz</td></tr> </table> 	switch-on level	0.7 U _B	switch-off level	0.4 U _B	input resistance	2.86 kΩ	input frequency	50 Hz	switch-on level	0.43...0.73 U _B	switch-off level	0.29 U _B	input resistance	2.86 kΩ	input frequency max.	50 kHz												
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<p>Test input</p>	<p>During the test mode (e.g. programming), the "TEST" connection must be connected to VBB_S (10...32 V DC). For the "RUN" mode, the test input must not be connected. Input resistance 3.21 kΩ</p>																												
<p>* NAMUR inputs</p>	<ul style="list-style-type: none"> ■ Digital inputs with diagnostic capability can be used as NAMUR inputs when used with an external resistor connection. <table border="0" style="width: 100%;"> <tr><td>supply voltage</td><td>5...25 V</td></tr> </table> <p>Wiring see page 5</p>	supply voltage	5...25 V																										
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Outputs (B_H, PWM, PWM)

%QX0.00...07

Can be configured as ...

- Semiconductor outputs, with diagnostic capability positive switching (high side), short-circuit and overload protected

switching voltage	10...32 V DC
switching current	max. 4 A
output frequency	max. 100 Hz (depending on the load)

- PWM outputs, diagnosis via current feedback

PWM frequency	max. 250 Hz
mark-to-space ratio	1...99 %
resolution	depends on the PWM frequency
load current	max. 4 A
integrated pull-down resistor	(4.7 kΩ)

- Current-controlled outputs, diagnosis via current feedback

load current	0,1...4 A
load resistance	min. 3 Ω (at UB = 12 V DC)
	min. 6 Ω (at UB = 24 V DC)
setting resolution	1 mA
control resolution	5 mA
accuracy	± 2% FS

Overload protection

(valid for all outputs)

max. 5 minutes (at 100%)

Internal relay outputs

For electrically isolated deactivation of the outputs

Normally open contacts in series to 2 groups of 4 semiconductor outputs.
Sustained forcing by means of hardware and additional controlling by means of user program.
The relays must always be switched without load!

- | | |
|----------------------------|----------------------------------|
| total current max. | 12 A per group |
| switching current | 0.1...15 A |
| overload current | 20 A |
| number of operating cycles | ≥ 10 ⁶ (without load) |
| switching-time constant | ≤ 3 ms |

Output error

- Semiconductor output, positive switching (high side)

switching voltage	10...32 V DC
switching current	max. 100 mA
overload current	0.5 A
switching function	OFF (0 V) in case of an error

Wiring see page 5

Wiring

Pin	Potential	Description	Note
23	VBB _S (10...32 V DC)	Supply sensors and module	
05	VBB _O (10...32 V DC)	Supply outputs	Relay switched (1)
34	VBB _R (10...32 V DC)	Supply via relay	Relay switched (2)
01	GND _S	Ground sensors and module	
15	GND _O	Ground outputs	
12	GND _A	Ground analog outputs	

CAN, RS-232, ERROR, TEST

Pin	Potential	Description	Note
14	CAN1 _H	CAN-Interface 1 (high)	
32	CAN1 _L	CAN-Interface 1 (low)	
26	CAN2 _H	CAN-Interface 2 (high)	SAE J1939
25	CAN2 _L	CAN-Interface 2 (low)	SAE J1939
33	GND	Ground (RS-232/CAN)	
06	RxD	RS-232 Interface (programming)	Pin 03, PC D-Sub (9 pin)
07	TxD	RS-232 Interface (programming)	Pin 02, PC D-Sub (9 pin)
13	ERROR	Error output B H	
24	TEST	Test input	

Inputs/Outputs

Pin	Inputs	Configuration	Outputs	Configuration	Diagnostic capability* Input/Output	Relay switched
08	%IX0.00 / %IW03	B _L A	–	–	•/–	
27	%IX0.01 / %IW04	B _L A	–	–	•/–	
09	%IX0.02 / %IW05	B _L A	–	–	•/–	
28	%IX0.03 / %IW06	B _L A	–	–	•/–	
10	%IX0.04 / %IW07	B _L A	–	–	•/–	
29	%IX0.05 / %IW08	B _L A	–	–	•/–	
11	%IX0.06 / %IW09	B _L A	–	–	•/–	
30	%IX0.07 / %IW10	B _L A	–	–	•/–	
44	%IX0.08	B _L	%QX0.00	B _H PWM PWM _I	–/•	VBB _O (1)
45	%IX0.09	B _L	%QX0.01	B _H PWM PWM _I	–/•	VBB _O (1)
46	%IX0.10	B _L	%QX0.02	B _H PWM PWM _I	–/•	VBB _O (1)
47	%IX0.11	B _L	%QX0.03	B _H PWM PWM _I	–/•	VBB _O (1)
20	%IX0.12	B _L I _L	(FRQ 0) –	–	•/–	
02	%IX0.13	B _L I _L	(FRQ 1) –	–	•/–	
21	%IX0.14	B _L I _L	(FRQ 2) –	–	•/–	
38	%IX0.15	B _L I _L	(FRQ 3) –	–	•/–	
36	%IX1.00	B _L	%QX0.04	B _H PWM PWM _I	–/•	VBB _R (2)
54	%IX1.01	B _L	%QX0.05	B _H PWM PWM _I	–/•	VBB _R (2)
17	%IX1.02	B _L	%QX0.06	B _H PWM PWM _I	–/•	VBB _R (2)
53	%IX1.03	B _L	%QX0.07	B _H PWM PWM _I	–/•	VBB _R (2)
19	%IX1.04	B _{LH} I _L	(CYL 0) –	–	• / –	
55	%IX1.05	B _{LH} I _L	(CYL 1) –	–	•/–	
18	%IX1.06	B _{LH} I _L	(CYL 2) –	–	•/–	
37	%IX1.07	B _{LH} I _L	(CYL 3) –	–	•/–	

Note the double pin connection of inputs/outputs.

*Only positive sensor signals with diagnostic capability

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