



Version: 3.9

IL026011EN Build 59947

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1 Modbus Parameters

For the Modbus Protocol several parameters have to be set which are relevant for the communication between the control system (SCADA) and the device. The parameters and their setting possibilities or value ranges are shown in the tables below.

NOTICE!



The Parameters are described within the Reference Manual of the device (separate document).

1.1 Notes for the SCADA-System

When using Modbus RTU the following times have to be considered by the control system and are fixed within the device:

The dwell times (t_D) before start of a telegram must be set at least to 3.5 characters.

Examples:

- 3.5 characters 9600 Baud = 4 ms
- 3.5 characters 19200 Baud = 2 ms
- 3.5 characters 38400 Baud = 1 ms

Start of a new telegram is expected when the dwell time (t_D) is > 3.5 characters.

The fact that the probability of disruptions during transmission of a telegram increases with its length has to be taken into duly consideration and thus a query to the Slave should be possibly such that the response telegram is not much longer than 32 Bytes.

2 Specific Modbus Function Codes

For reading out data from the device or to carry out commands, the services listed in the table, also called »Function Codes«, are supported.

Function Code	Designation	Description
3	Read Holding Registers	There are single or several data words read as from a specific data word address. Only status addresses and parameter addresses can be read.
4	Read Input Registers	There are single or several data words read as from a specific data word address. Only measuring values can be read.
5	Write single Output (Bit)	All other values are illegal and will not affect the output. Via this function code acknowledgments can be executed as well as counters reseted or blockings set.
8	Loopback Test	Test function for the communication system.
16	Load Multiple Registers	There are single or several data words written as from a specific data word address.

On the following pages the Modbus functions are described in detail.

2.1 Function Code 3/4

Query

Slave address	3/4	Register address	Register address	Register number	Register number	Check-sum	Check-sum
		HI	LO	HI	LO	HI	LO

Response

Slave address	3/4	Byte number	Register 0	Register 0	...	Check-sum	Check-sum
			HI	LO		HI	LO

Register address (HI · 256 + LO) — The data word address from where reading should start.

Register number (HI · 256 + LO) — Number of data words to be read. Valid range: 1...125

Byte number — Number of subsequent Bytes containing data words.

Register — Data words read out of the device (Highbyte and Lowbyte).

2.2 Function Code 5

Query

Slave address	5	Register address	Register address	Register data	Register data	Check-sum	Check-sum
		HI	LO	HI	LO	HI	LO

Response

Slave address	5	Register address	Register address	Register data	Register data	Check-sum	Check-sum
		HI	LO	HI	LO	HI	LO

Register address (HI · 256 + LO) — Data word address to be written

Register data — Value of the data word to be written (High-byte and Low-byte).

Permitted value range:

- FF00 hex request for a single bit to be on: This often means to reset a counter, execute acknowledgments or set blockings signals.
- 0000 hex request for a single bit to be off: This often means to deactivate blocking signals or to reset single bits.

2.3 Function Code 8

Query

Slave address	8	Data Diag	Data Diag	Test data	Test data	Check-sum	Check-sum
		Code HI	Code LO			HI	LO
		0x00	0x00				

Response

Slave address	8	Data Diag	Data Diag	Test data	Test data	Check-sum	Check-sum
		Code HI	Code LO			HI	LO

Data Diag Code HI (high), Data Diag Code LO (Low) — Diagnostic Code (subfunction code of function code 8) for testing the communication system. The Diagnostic Code “Return Query Data” (0x00, 0x00) is being supported.

Test Data — By using the Diagnostic Code 0x00 0x00, the transmitted data is sent back to the Master unchanged.

2.4 Function Code 16

Query

Slave address	16	Register address	Register address	Register number	Register number	Byte number	Register 0	Register 0	...	Check-sum	Check-sum
		HI	LO	HI	LO		HI	LO		HI	LO

Response

Slave address	16	Register address	Register address	Register number	Register number	Check-sum	Check-sum
		HI	LO	HI	LO	HI	LO

Register address (HI · 256 + LO) — Data word address as from where writing should start.

Register number (HI · 256 + LO):

- Query: Number of data words to be written. Valid range: 1...123.
- Response: Number of data words written.

Byte number — Number of subsequent Bytes to contain data words.

Register — Data words read out of the device (High-byte and Low-byte).

2.5 Setting Date and Time

Date and time can be set by means of function code 16 and read with function code 3. If the device address 0 (broadcast address) is selected, the times of all devices connected to this bus are simultaneously reset.

NOTICE!



The devices do not respond to a broadcast command.

2.6 Supported MODBUS Error Messages

Exception Response Telegrams are described within the general "Modbus Application Protocol Specification". An exception response table with examples is shown there. The table below contains just the actually used codes. In case the device has recognized an error it will react in the following way:

Exception Code	Designation	Description
1	Illegal Function	The message received includes a function code which is not supported by the Slave.
2	Illegal Data Address	Access was sought on a data word address not included in the data module.
3	Illegal Data Value	The received message contains an invalid data structure (e. g. wrong number of data bytes).
4	Slave Device Failure	An unrecoverable error occurred while the server (or slave) was attempting to perform the requested action.

The response given by the *device* in case of a failure has the following format:

Slave Address	0x80	Exception Code	Check-sum	Check-sum
	+ Function Code		HI	LO

In the second Byte of the response the Function Code is sent with the highest Bit set to 1. This is equivalent to an addition by 0x80. The third Byte holds the Exception Code of the error message.

3 Appendix - Register Maps

3.1 Signals

Legend: (*) = These signals have to be acknowledged by the Scada System.

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
37[1] - Underload		167	1	3	Struct			
	Active	167	1	3	Bit	0x10 (5)	-	Signal: Active
	Pickup	167	1	3	Bit	0x200 (10)	-	Signal: Pickup
	Trip (*)	167	1	3	Bit	0x400 (11)	-	Signal: Trip
37[2] - Underload		168	1	3	Struct			
	Active	168	1	3	Bit	0x10 (5)	-	Signal: Active
	Pickup	168	1	3	Bit	0x200 (10)	-	Signal: Pickup
	Trip (*)	168	1	3	Bit	0x400 (11)	-	Signal: Trip
46[1] - I.Unbalance		82	1	3	Struct			
	Active	82	1	3	Bit	0x8	-	Signal: Active

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(4)		
	Pickup	82	1	3	Bit	0x80 (8)	-	Signal: Pickup Negative Sequence
	Trip (*)	82	1	3	Bit	0x100 (9)	-	Signal: Trip
46[2] - I.Unbalance		83	1	3	Struct			
	Active	83	1	3	Bit	0x8 (4)	-	Signal: Active
	Pickup	83	1	3	Bit	0x80 (8)	-	Signal: Pickup Negative Sequence
	Trip (*)	83	1	3	Bit	0x100 (9)	-	Signal: Trip
49 - Thermal Model		164	1	3	Struct			
	Active	164	1	3	Bit	0x8 (4)	-	Signal: Active
	Pickup	164	1	3	Bit	0x80 (8)	-	Signal: Pickup
	Trip (*)	164	1	3	Bit	0x100 (9)	-	Signal: Trip
	Alarm Pickup	164	1	3	Bit	0x400 (11)	-	Signal: Alarm Pickup

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	Alarm Timeout	164	1	3	Bit	0x800 (12)	-	Signal: Alarm Timeout
	Load above SF	164	1	3	Bit	0x1000 (13)	-	“Load above Service Factor”: If the current exceeds the set value of “UTC” (“Ultimate trip threshold”) then the used thermal capacity counts up and the state “Load above SF” is becoming true. If the current is below the “UTC” value this state is false.
	RTD effective	164	1	3	Bit	0x2000 (14)	-	This state becomes true if the following conditions are all fulfilled: - the state “Load above SF” is true, - the Winding Temperature Trip has been activated in the RTD module, - for at least one temperature a valid value above 0°C (32°F) is being displayed.
50J[1] - Jam-Stall		165	1	3	Struct			
	Active	165	1	3	Bit	0x10 (5)	-	Signal: Active
	Pickup	165	1	3	Bit	0x200 (10)	-	Signal: Pickup
	Trip (*)	165	1	3	Bit	0x400 (11)	-	Signal: Trip
50J[2] - Jam-Stall		166	1	3	Struct			
	Active	166	1	3	Bit	0x10 (5)	-	Signal: Active

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	Pickup	166	1	3	Bit	0x200 (10)	-	Signal: Pickup
	Trip (*)	166	1	3	Bit	0x400 (11)	-	Signal: Trip
50P[1] - Phase Inst. OC		3	1	3	Struct			
	Active	3	1	3	Bit	0x10 (5)	-	Signal: Active
50P[1] - Phase Inst. OC		4	1	3	Struct			
	Pickup IA	4	1	3	Bit	0x1 (1)	-	Signal: Pickup IA
	Pickup IB	4	1	3	Bit	0x2 (2)	-	Signal: Pickup IB
	Pickup IC	4	1	3	Bit	0x4 (3)	-	Signal: Pickup IC
	Pickup	4	1	3	Bit	0x8 (4)	-	Signal: Pickup
	Trip (*)	4	1	3	Bit	0x80 (8)	-	Signal: Trip
50P[2] - Phase Inst. OC		5	1	3	Struct			
	Active	5	1	3	Bit	0x10	-	Signal: Active

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(5)		
50P[2] - Phase Inst. OC		6	1	3	Struct			
	Pickup IA	6	1	3	Bit	0x1 (1)	-	Signal: Pickup IA
	Pickup IB	6	1	3	Bit	0x2 (2)	-	Signal: Pickup IB
	Pickup IC	6	1	3	Bit	0x4 (3)	-	Signal: Pickup IC
	Pickup	6	1	3	Bit	0x8 (4)	-	Signal: Pickup
	Trip (*)	6	1	3	Bit	0x80 (8)	-	Signal: Trip
50X[1] - Meas. Inst. OC		15	1	3	Struct			
	Active	15	1	3	Bit	0x10 (5)	-	Signal: Active
	Pickup	15	1	3	Bit	0x400 (11)	-	Signal: The pickup value has been exceeded.
	Trip (*)	15	1	3	Bit	0x800 (12)	-	Signal: Trip
50X[2] - Meas. Inst. OC		16	1	3	Struct			
	Active	16	1	3	Bit	0x10	-	Signal: Active

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(5)		
	Pickup	16	1	3	Bit	0x400 (11)	-	Signal: The pickup value has been exceeded.
	Trip (*)	16	1	3	Bit	0x800 (12)	-	Signal: Trip
DI Slot X1		1000	1	3	Struct			
	DI 1	1000	1	3	Bit	0x10 (5)	-	Signal: Digital Input
	DI 2	1000	1	3	Bit	0x20 (6)	-	Signal: Digital Input
	DI 3	1000	1	3	Bit	0x40 (7)	-	Signal: Digital Input
	DI 4	1000	1	3	Bit	0x80 (8)	-	Signal: Digital Input
Ex87		223	1	3	Struct			
	Alarm-I	223	1	3	Bit	0x1 (1)	-	Module Input State: Alarm
	Trip-I (*)	223	1	3	Bit	0x10 (5)	-	Module Input State: Trip
	Alarm	223	1	3	Bit	0x20 (6)	-	Signal: Alarm
	Active	223	1	3	Bit	0x40	-	Signal: Active

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(7)		
	Trip (*)	223	1	3	Bit	0x100 (9)	-	Signal: Trip
Fast Status Register		5000	1	3	Struct			
	Device Type	5000	1	3	Bit	0xffff (1)	-	Device type code for relationship between device name and its Modbus code. For Eaton E-Series: EDR-3000 - 2 EDR-5000 - 3 EMR-3000 - 4 EMR-3MP0 - 4 EMR-4000 - 5 EMR-5000 - 6 ETR-4000 - 8 ETR-5000 - 9 EGR-5000 - 12 EBR-3000 - 13
Fast Status Register		5001	1	3	Struct			
	Comm Version	5001	1	3	Bit	0xffff (1)	-	Modbus Communication version. This version number changes if something becomes incompatible between different Modbus releases.
Fast Status Register		5002	1	3	Struct			

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	Config Bin Inp1-l	5002	1	3	Bit	0x1 (1)	-	State of the module input: Config Bin Inp
	Config Bin Inp2-l	5002	1	3	Bit	0x2 (2)	-	State of the module input: Config Bin Inp
	Config Bin Inp3-l	5002	1	3	Bit	0x4 (3)	-	State of the module input: Config Bin Inp
	Config Bin Inp4-l	5002	1	3	Bit	0x8 (4)	-	State of the module input: Config Bin Inp
	Config Bin Inp5-l	5002	1	3	Bit	0x10 (5)	-	State of the module input: Config Bin Inp
	Config Bin Inp6-l	5002	1	3	Bit	0x20 (6)	-	State of the module input: Config Bin Inp
	Config Bin Inp7-l	5002	1	3	Bit	0x40 (7)	-	State of the module input: Config Bin Inp
	Config Bin Inp8-l	5002	1	3	Bit	0x80 (8)	-	State of the module input: Config Bin Inp
	Config Bin Inp9-l	5002	1	3	Bit	0x100 (9)	-	State of the module input: Config Bin Inp
	Config Bin Inp10-l	5002	1	3	Bit	0x200 (10)	-	State of the module input: Config Bin Inp
	Config Bin Inp11-l	5002	1	3	Bit	0x400	-	State of the module input: Config Bin Inp

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(11)		
	Config Bin Inp12-I	5002	1	3	Bit	0x800 (12)	-	State of the module input: Config Bin Inp
	Config Bin Inp13-I	5002	1	3	Bit	0x1000 (13)	-	State of the module input: Config Bin Inp
	Config Bin Inp14-I	5002	1	3	Bit	0x2000 (14)	-	State of the module input: Config Bin Inp
	Config Bin Inp15-I	5002	1	3	Bit	0x4000 (15)	-	State of the module input: Config Bin Inp
	Config Bin Inp16-I	5002	1	3	Bit	0x8000 (16)	-	State of the module input: Config Bin Inp
Fast Status Register		5003	1	3	Struct			
	Config Bin Inp17-I	5003	1	3	Bit	0x1 (1)	-	State of the module input: Config Bin Inp
	Config Bin Inp18-I	5003	1	3	Bit	0x2 (2)	-	State of the module input: Config Bin Inp
	Config Bin Inp19-I	5003	1	3	Bit	0x4 (3)	-	State of the module input: Config Bin Inp
	Config Bin Inp20-I	5003	1	3	Bit	0x8 (4)	-	State of the module input: Config Bin Inp
	Config Bin Inp21-I	5003	1	3	Bit	0x10	-	State of the module input: Config Bin Inp

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(5)		
	Config Bin Inp22-I	5003	1	3	Bit	0x20 (6)	-	State of the module input: Config Bin Inp
	Config Bin Inp23-I	5003	1	3	Bit	0x40 (7)	-	State of the module input: Config Bin Inp
	Config Bin Inp24-I	5003	1	3	Bit	0x80 (8)	-	State of the module input: Config Bin Inp
	Config Bin Inp25-I	5003	1	3	Bit	0x100 (9)	-	State of the module input: Config Bin Inp
	Config Bin Inp26-I	5003	1	3	Bit	0x200 (10)	-	State of the module input: Config Bin Inp
	Config Bin Inp27-I	5003	1	3	Bit	0x400 (11)	-	State of the module input: Config Bin Inp
	Config Bin Inp28-I	5003	1	3	Bit	0x800 (12)	-	State of the module input: Config Bin Inp
	Config Bin Inp29-I	5003	1	3	Bit	0x1000 (13)	-	State of the module input: Config Bin Inp
	Config Bin Inp30-I	5003	1	3	Bit	0x2000 (14)	-	State of the module input: Config Bin Inp
	Config Bin Inp31-I	5003	1	3	Bit	0x4000 (15)	-	State of the module input: Config Bin Inp

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	Config Bin Inp32-I	5003	1	3	Bit	0x8000 (16)	-	State of the module input: Config Bin Inp
Fast Status Register		5004	1	3	Struct			
	Trip Cause (*)	5004	1	3	Bit	0xffff (1)	-	Initial reason of trip. It is presented as an integer value and corresponds to the "Trip" entry in the fault record, which refers to the name of the protective module that tripped first. Look up the definition of these integer values (i. e. the mapping trip code number->module name) in the "Cause of Trip" table within the SCADA documentation.
IRIG-B		148	1	3	Struct			
	IRIG-B active	148	1	3	Bit	0x1 (1)	-	Signal: If there is no valid IRIG-B signal for 60 sec, IRIG-B is regarded as inactive.
	High-Low Invert	148	1	3	Bit	0x2 (2)	-	Signal: The High and Low signals of the IRIG-B are inverted. This does NOT mean that the wiring is faulty. If the wiring is faulty no IRIG-B signal will be detected.
Logic		1100	1	3	Struct			
	LE1.Gate Out	1100	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE1.Timer Out	1100	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE1.Out	1100	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE1.Out inverted	1100	1	3	Bit	0x8	-	Signal: Negated Latched Output (Q NOT)

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(4)		
	LE1.Gate In1-I	1100	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE1.Gate In2-I	1100	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE1.Gate In3-I	1100	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE1.Gate In4-I	1100	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE1.Reset Latch-I	1100	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1101	1	3	Struct			
	LE2.Gate Out	1101	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE2.Timer Out	1101	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE2.Out	1101	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE2.Out inverted	1101	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE2.Gate In1-I	1101	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE2.Gate In2-I	1101	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE2.Gate In3-I	1101	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE2.Gate In4-I	1101	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE2.Reset Latch-I	1101	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1102	1	3	Struct			
	LE3.Gate Out	1102	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE3.Timer Out	1102	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE3.Out	1102	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE3.Out inverted	1102	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE3.Gate In1-I	1102	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE3.Gate In2-I	1102	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE3.Gate In3-I	1102	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE3.Gate In4-I	1102	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE3.Reset Latch-I	1102	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1103	1	3	Struct			
	LE4.Gate Out	1103	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE4.Timer Out	1103	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE4.Out	1103	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE4.Out inverted	1103	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE4.Gate In1-I	1103	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE4.Gate In2-I	1103	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE4.Gate In3-I	1103	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE4.Gate In4-I	1103	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE4.Reset Latch-I	1103	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1104	1	3	Struct			
	LE5.Gate Out	1104	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE5.Timer Out	1104	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE5.Out	1104	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE5.Out inverted	1104	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE5.Gate In1-I	1104	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE5.Gate In2-I	1104	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE5.Gate In3-I	1104	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE5.Gate In4-I	1104	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE5.Reset Latch-I	1104	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1105	1	3	Struct			
	LE6.Gate Out	1105	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE6.Timer Out	1105	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE6.Out	1105	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE6.Out inverted	1105	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE6.Gate In1-I	1105	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE6.Gate In2-I	1105	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE6.Gate In3-I	1105	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE6.Gate In4-I	1105	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE6.Reset Latch-I	1105	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1106	1	3	Struct			

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE7.Gate Out	1106	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE7.Timer Out	1106	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE7.Out	1106	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE7.Out inverted	1106	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE7.Gate In1-I	1106	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE7.Gate In2-I	1106	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE7.Gate In3-I	1106	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE7.Gate In4-I	1106	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE7.Reset Latch-I	1106	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1107	1	3	Struct			
	LE8.Gate Out	1107	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE8.Timer Out	1107	1	3	Bit	0x2	-	Signal: Timer Output

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(2)		
	LE8.Out	1107	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE8.Out inverted	1107	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE8.Gate In1-I	1107	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE8.Gate In2-I	1107	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE8.Gate In3-I	1107	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE8.Gate In4-I	1107	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE8.Reset Latch-I	1107	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1108	1	3	Struct			
	LE9.Gate Out	1108	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE9.Timer Out	1108	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE9.Out	1108	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE9.Out inverted	1108	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE9.Gate In1-I	1108	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE9.Gate In2-I	1108	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE9.Gate In3-I	1108	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE9.Gate In4-I	1108	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE9.Reset Latch-I	1108	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1109	1	3	Struct			
	LE10.Gate Out	1109	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE10.Timer Out	1109	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE10.Out	1109	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE10.Out inverted	1109	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE10.Gate In1-I	1109	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE10.Gate In2-I	1109	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE10.Gate In3-I	1109	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE10.Gate In4-I	1109	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE10.Reset Latch-I	1109	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1110	1	3	Struct			
	LE11.Gate Out	1110	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE11.Timer Out	1110	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE11.Out	1110	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE11.Out inverted	1110	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE11.Gate In1-I	1110	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE11.Gate In2-I	1110	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE11.Gate In3-I	1110	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE11.Gate In4-I	1110	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE11.Reset Latch-I	1110	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1111	1	3	Struct			
	LE12.Gate Out	1111	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE12.Timer Out	1111	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE12.Out	1111	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE12.Out inverted	1111	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE12.Gate In1-I	1111	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE12.Gate In2-I	1111	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE12.Gate In3-I	1111	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE12.Gate In4-I	1111	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE12.Reset Latch-I	1111	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1112	1	3	Struct			
	LE13.Gate Out	1112	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE13.Timer Out	1112	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE13.Out	1112	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE13.Out inverted	1112	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE13.Gate In1-I	1112	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE13.Gate In2-I	1112	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE13.Gate In3-I	1112	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE13.Gate In4-I	1112	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE13.Reset Latch-I	1112	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1113	1	3	Struct			
	LE14.Gate Out	1113	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE14.Timer Out	1113	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE14.Out	1113	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE14.Out inverted	1113	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE14.Gate In1-I	1113	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE14.Gate In2-I	1113	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE14.Gate In3-I	1113	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE14.Gate In4-I	1113	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE14.Reset Latch-I	1113	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1114	1	3	Struct			
	LE15.Gate Out	1114	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE15.Timer Out	1114	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE15.Out	1114	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE15.Out inverted	1114	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE15.Gate In1-I	1114	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE15.Gate In2-I	1114	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE15.Gate In3-I	1114	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE15.Gate In4-I	1114	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE15.Reset Latch-I	1114	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1115	1	3	Struct			

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE16.Gate Out	1115	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE16.Timer Out	1115	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE16.Out	1115	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE16.Out inverted	1115	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE16.Gate In1-I	1115	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE16.Gate In2-I	1115	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE16.Gate In3-I	1115	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE16.Gate In4-I	1115	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE16.Reset Latch-I	1115	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1116	1	3	Struct			
	LE17.Gate Out	1116	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE17.Timer Out	1116	1	3	Bit	0x2	-	Signal: Timer Output

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(2)		
	LE17.Out	1116	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE17.Out inverted	1116	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE17.Gate In1-I	1116	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE17.Gate In2-I	1116	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE17.Gate In3-I	1116	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE17.Gate In4-I	1116	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE17.Reset Latch-I	1116	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1117	1	3	Struct			
	LE18.Gate Out	1117	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE18.Timer Out	1117	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE18.Out	1117	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE18.Out inverted	1117	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE18.Gate In1-I	1117	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE18.Gate In2-I	1117	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE18.Gate In3-I	1117	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE18.Gate In4-I	1117	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE18.Reset Latch-I	1117	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1118	1	3	Struct			
	LE19.Gate Out	1118	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE19.Timer Out	1118	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE19.Out	1118	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE19.Out inverted	1118	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE19.Gate In1-I	1118	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal
	LE19.Gate In2-I	1118	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE19.Gate In3-I	1118	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE19.Gate In4-I	1118	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE19.Reset Latch-I	1118	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
Logic		1119	1	3	Struct			
	LE20.Gate Out	1119	1	3	Bit	0x1 (1)	-	Signal: Output of the logic gate
	LE20.Timer Out	1119	1	3	Bit	0x2 (2)	-	Signal: Timer Output
	LE20.Out	1119	1	3	Bit	0x4 (3)	-	Signal: Latched Output (Q)
	LE20.Out inverted	1119	1	3	Bit	0x8 (4)	-	Signal: Negated Latched Output (Q NOT)
	LE20.Gate In1-I	1119	1	3	Bit	0x10 (5)	-	State of the module input: Assignment of the Input Signal

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	LE20.Gate In2-I	1119	1	3	Bit	0x20 (6)	-	State of the module input: Assignment of the Input Signal
	LE20.Gate In3-I	1119	1	3	Bit	0x40 (7)	-	State of the module input: Assignment of the Input Signal
	LE20.Gate In4-I	1119	1	3	Bit	0x80 (8)	-	State of the module input: Assignment of the Input Signal
	LE20.Reset Latch-I	1119	1	3	Bit	0x100 (9)	-	State of the module input: Reset Signal for the Latching
MLS - Mech.Load Shedding		170	1	3	Struct			
	Active	170	1	3	Bit	0x4 (3)	-	Signal: Active
	Pickup	170	1	3	Bit	0x10 (5)	-	Signal: Pickup
	Trip	170	1	3	Bit	0x20 (6)	-	Signal: Trip
MStart - Motor Start		160	1	3	Struct			
	Blo	160	1	3	Bit	0x40 (7)	-	Signal: Motor is blocked for starting or transition to Run mode
	ThermalBlock	160	1	3	Bit	0x80 (8)	-	Signal: Thermal block

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	EmgOvr-I	160	1	3	Bit	0x100 (9)	-	State of the module input: Emergency Override. Signal has to be active in order to release the thermal capacity of the motor. Please notice that by doing this you run the risk of damaging the motor. "EMGOVR" has to be set to "DI" or "DI or UI" for this input to take effect
	InSq-I	160	1	3	Bit	0x200 (10)	-	State of the module input: Incomplete Sequence
MStart - Motor Start		161	1	3	Struct			
	RemStartBlock-I	161	1	3	Bit	0x2 (2)	-	State of the module input: Remote Motor Start Blocking
	ZSS-I	161	1	3	Bit	0x10 (5)	-	State of the module input: Zero Speed Switch
	Active	161	1	3	Bit	0x80 (8)	-	Signal: Active
	Trip (*)	161	1	3	Bit	0x400 (11)	-	Signal: Trip
	InSq Start2Run Fail	161	1	3	Bit	0x1000 (13)	-	Signal: Fail to transit from start to run based on reported back time
	InSq Stop2Start Fail	161	1	3	Bit	0x2000 (14)	-	Signal: Fail to transit from stop to start based on reported back time
	LATBlock	161	1	3	Bit	0x4000 (15)	-	Signal: Long acceleration timer enforced

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	TripPhaseReverse (*)	161	1	3	Bit	0x8000 (16)	-	Signal: Relay tripped because of phase reverse detection
MStart - Motor Start		162	1	3	Struct			
	NOCSBlocked	162	1	3	Bit	0x1 (1)	-	Signal: Motor is prohibited to start due to number of cold start limits
	RemBlockStart	162	1	3	Bit	0x2 (2)	-	Signal: Motor is prohibited to start due to external blocking through digital input DI
	Run	162	1	3	Bit	0x4 (3)	-	Signal: Motor is in run mode
	Start	162	1	3	Bit	0x8 (4)	-	Signal: Motor is in start mode
	SPHBlockAlarm	162	1	3	Bit	0x10 (5)	-	Signal: Motor is prohibited to start due to starts per hour limits, would come active in the next stop
	SPHBlocked	162	1	3	Bit	0x20 (6)	-	Signal: Motor is prohibited to start due to starts per hour limits
	Stop	162	1	3	Bit	0x40 (7)	-	Signal: Motor is in stop mode
	TBSBlocked	162	1	3	Bit	0x80 (8)	-	Signal: Motor is prohibited to start due to time between starts limits
	TransitionTrip (*)	162	1	3	Bit	0x100 (9)	-	Signal: Start transition fail trip

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	ZSSTrip (*)	162	1	3	Bit	0x200 (10)	-	Signal: Zero speed trip (possible locked rotor)
	ABKActive	162	1	3	Bit	0x400 (11)	-	Signal: Anti-backspin is active. For certain applications, such as pumping a fluid up a pipe, the motor may be driven backward for a period of time after it stops. The anti-backspin timer prevents starting the motor while it is spinning in the reverse direction.
	EmergOverrideDI	162	1	3	Bit	0x800 (12)	-	Signal: Emergency override start blocking through digital input DI
	EmergOverrideUI	162	1	3	Bit	0x1000 (13)	-	Signal: Emergency override start blocking through front panel
	ForcedStart	162	1	3	Bit	0x2000 (14)	-	Signal: Motor being forced to start
	GOCStartBlock	162	1	3	Bit	0x4000 (15)	-	Signal: Ground Instantaneous Overcurrent Start Delay. GOC (Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
	IOCStartBlock	162	1	3	Bit	0x8000 (16)	-	Signal: Phase Instantaneous Overcurrent Start Delay. IOC (Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
MStart - Motor Start		163	1	3	Struct			
	JamStartBlock	163	1	3	Bit	0x1 (1)	-	Signal: JAM Start Delay. JAM(Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
	ULoadStartBlock	163	1	3	Bit	0x2	-	Signal: Underload Start Delay. Underload(Instantaneous Overcurrent)

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(2)		elements are blocked for the time programmed under this parameter
	IUnbalStartBlock	163	1	3	Bit	0x4 (3)	-	Signal: Motor start block current unbalance signal
	ColdStartSeq	163	1	3	Bit	0x8 (4)	-	Signal: Motor cold start sequence flag
	MotorStopBlo	163	1	3	Bit	0x20 (6)	-	Signal: Motor stop block other protection functions
	I_Transit	163	1	3	Bit	0x800 (12)	-	Signal: Current transition signal
	T_Transit	163	1	3	Bit	0x1000 (13)	-	Signal: Time transition signal
	RFD_IA_Normal	163	1	3	Bit	0x2000 (14)	-	Signal: System IA RotaryFieldDetection Normal
	RFD_IA_Reverse	163	1	3	Bit	0x4000 (15)	-	Signal: System IA RotaryFieldDetection Reverse
	STPC Blo-I	163	1	3	Bit	0x8000 (16)	-	State of the module input: With this setting a Digital Input keeps the Motor in the RUN mode, even when the motor current drops below STPC (motor stop current).
Modbus		1005	1	3	Struct			
	Comm Cmd 1	1005	1	3	Bit	0x1 (1)	-	Communication Command
	Comm Cmd 2	1005	1	3	Bit	0x2	-	Communication Command

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(2)		
	Comm Cmd 3	1005	1	3	Bit	0x4 (3)	-	Communication Command
	Comm Cmd 4	1005	1	3	Bit	0x8 (4)	-	Communication Command
	Comm Cmd 5	1005	1	3	Bit	0x10 (5)	-	Communication Command
	Comm Cmd 6	1005	1	3	Bit	0x20 (6)	-	Communication Command
	Comm Cmd 7	1005	1	3	Bit	0x40 (7)	-	Communication Command
	Comm Cmd 8	1005	1	3	Bit	0x80 (8)	-	Communication Command
	Comm Cmd 9	1005	1	3	Bit	0x100 (9)	-	Communication Command
	Comm Cmd 10	1005	1	3	Bit	0x200 (10)	-	Communication Command
	Comm Cmd 11	1005	1	3	Bit	0x400 (11)	-	Communication Command
	Comm Cmd 12	1005	1	3	Bit	0x800 (12)	-	Communication Command
	Comm Cmd 13	1005	1	3	Bit	0x1000	-	Communication Command

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(13)		
	Comm Cmd 14	1005	1	3	Bit	0x2000 (14)	-	Communication Command
	Comm Cmd 15	1005	1	3	Bit	0x4000 (15)	-	Communication Command
	Comm Cmd 16	1005	1	3	Bit	0x8000 (16)	-	Communication Command
PSet-Switch		59	1	3	Struct			
	Min. 1 param changed (*)	59	1	3	Bit	0x800 (12)	-	Signal: At least one parameter has been changed
Prot		1	1	3	Struct			
	Active	1	1	3	Bit	0x4 (3)	-	Signal: Active
	Pickup Phase A	1	1	3	Bit	0x10 (5)	-	Signal: General Pickup Phase A
	Pickup Phase B	1	1	3	Bit	0x20 (6)	-	Signal: General Pickup Phase B
	Pickup Phase C	1	1	3	Bit	0x40 (7)	-	Signal: General Pickup Phase C
	Pickup IX	1	1	3	Bit	0x80 (8)	-	Signal: General Pickup - Ground Fault
	Pickup	1	1	3	Bit	0x100	-	Signal: General Pickup

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(9)		
	Trip Phase A (*)	1	1	3	Bit	0x200 (10)	-	Signal: General Trip Phase A
	Trip Phase B (*)	1	1	3	Bit	0x400 (11)	-	Signal: General Trip Phase B
	Trip Phase C (*)	1	1	3	Bit	0x800 (12)	-	Signal: General Trip Phase C
	Trip IX (*)	1	1	3	Bit	0x1000 (13)	-	Signal: General Trip Ground Fault
	Trip (*)	1	1	3	Bit	0x2000 (14)	-	Signal: General Trip
Prot		57	1	3	Struct			
	Fault No.	57	1	3	Bit	0xffff (1)	-	Waveform number
RO-3AI X2 - 3 und Life MK Reduced		1003	1	3	Struct			
	RO 1	1003	1	3	Bit	0x4 (3)	-	Signal: Relay Output
	RO 2	1003	1	3	Bit	0x8 (4)	-	Signal: Relay Output
	RO 3	1003	1	3	Bit	0x10 (5)	-	Signal: Relay Output

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	DISARMED!	1003	1	3	Bit	0x40 (7)	-	Signal: CAUTION! RELAYS DISARMED in order to safely perform maintenance while eliminating the risk of taking an entire process off-line. (Note: Zone Interlocking and Supervision Contact cannot be disarmed). YOU MUST ENSURE that the relays are ARMED AGAIN after maintenance
	Outs forced	1003	1	3	Bit	0x80 (8)	-	Signal: The State of at least one Relay Output has been set by force. That means that the state of at least one Relay is forced and hence does not show the state of the assigned signals.
RTD		143	1	3	Struct			
	Active	143	1	3	Bit	0x8 (4)	-	Signal: Active
	Alarm	143	1	3	Bit	0x80 (8)	-	Alarm RTD Temperature Protection
	Trip (*)	143	1	3	Bit	0x100 (9)	-	Signal: Trip
RTD		146	1	3	Struct			
	WD Group Invalid	146	1	3	Bit	0x1000 (13)	-	Winding Group Signal: Invalid Temperature Measurement Value (e.g caused by a defective or interrupted RTD Measurement)
	MB Group Invalid	146	1	3	Bit	0x2000 (14)	-	Motor Bearing Group Signal: Invalid Temperature Measurement Value (e.g caused by a defective or interrupted RTD Measurement)
	Timeout Alarm (*)	146	1	3	Bit	0x4000 (15)	-	Alarm timeout expired

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
RTD		147	1	3	Struct			
	LB Group Invalid	147	1	3	Bit	0x1 (1)	-	Load Bearing Group Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
	Alarm LB Group	147	1	3	Bit	0x2 (2)	-	Alarm all Load Bearings
	TimeoutAlmLBGrp	147	1	3	Bit	0x4 (3)	-	Timeout Alarm all Load Bearings
	Trip LB Group (*)	147	1	3	Bit	0x8 (4)	-	Trip all Load Bearings
	Alarm MB Group	147	1	3	Bit	0x10 (5)	-	Alarm all Motor Bearings
	TimeoutAlmMBGrp	147	1	3	Bit	0x20 (6)	-	Timeout Alarm all Motor Bearings
	Trip MB Group (*)	147	1	3	Bit	0x40 (7)	-	Trip all Motor Bearings
	Alarm WD Group	147	1	3	Bit	0x80 (8)	-	Alarm all Windings
	TimeoutAlmWDGrp	147	1	3	Bit	0x100 (9)	-	Timeout Alarm all Windings
	Trip WD Group (*)	147	1	3	Bit	0x200 (10)	-	Trip all Windings

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
RTD		205	1	3	Struct			
	Alarm Any Group	205	1	3	Bit	0x1 (1)	-	Alarm Any Group
	Trip Any Group (*)	205	1	3	Bit	0x2 (2)	-	Trip Any Group
	TimeoutAlmAnyGrp	205	1	3	Bit	0x4 (3)	-	Timeout Alarm Any Group
	AuxGrpInvalid	205	1	3	Bit	0x80 (8)	-	Invalid Auxiliary Group
	Alarm Aux Group	205	1	3	Bit	0x100 (9)	-	Alarm Auxiliary Group
	TimeoutAlmAuxGrp	205	1	3	Bit	0x200 (10)	-	Timeout Alarm Auxiliary Group
	Trip Aux Group (*)	205	1	3	Bit	0x400 (11)	-	Trip Auxiliary Group
Remote Trip		222	1	3	Struct			
	Alarm-I	222	1	3	Bit	0x1 (1)	-	Module Input State: Alarm
	Trip-I (*)	222	1	3	Bit	0x10 (5)	-	Module Input State: Trip
	Alarm	222	1	3	Bit	0x20 (6)	-	Signal: Alarm

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	Active	222	1	3	Bit	0x40 (7)	-	Signal: Active
	Trip (*)	222	1	3	Bit	0x100 (9)	-	Signal: Trip
SSV		273	1	3	Struct			
	System Error	273	1	3	Bit	0x1 (1)	-	Signal: Device Failure
	New error (*)	273	1	3	Bit	0x8 (4)	-	Signal: A new error message has been issued.
	New warning (*)	273	1	3	Bit	0x10 (5)	-	Signal: A new warning message has been issued.
	Active	273	1	3	Bit	0x20 (6)	-	Signal: Active
Sgen		1012	1	3	Struct			
	ExBlo1-I	1012	1	3	Bit	0x1 (1)	-	Module Input State: External Blocking1
	Ex ForcePost-I	1012	1	3	Bit	0x2 (2)	-	State of the module input:Force Post state. Abort simulation.
	Running	1012	1	3	Bit	0x10 (5)	-	Signal: Measuring value simulation is running
	State	1012	1	3	Bit	0xe0 (6)	-	Signal: Wave generation states: 0=Off, 1=PreFault, 2=Fault, 3=PostFault, 4=InitReset

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	Ex Start Simulation-I	1012	1	3	Bit	0x100 (9)	-	State of the module input:External Start of Fault Simulation (Using the test parameters)
	ExBlo2-I	1012	1	3	Bit	0x200 (10)	-	Module Input State: External Blocking2
	Manual Start	1012	1	3	Bit	0x400 (11)	-	Fault Simulation has been started manually.
	Manual Stop	1012	1	3	Bit	0x800 (12)	-	Fault Simulation has been stopped manually.
	Started	1012	1	3	Bit	0x1000 (13)	-	Fault Simulation has been started
	Stopped	1012	1	3	Bit	0x2000 (14)	-	Fault Simulation has been stopped
Sys		154	1	3	Struct			
	SNTP active	154	1	3	Bit	0x80 (8)	-	Signal: If there is no valid SNTP signal for 120 sec, SNTP is regarded as inactive.
	Program Mode Bypass	154	1	3	Bit	0x100 (9)	-	Signal: Short-period bypass of the Program Mode.
TimeSync		54	1	3	Struct			
	synchronized	54	1	3	Bit	0x1 (1)	-	Clock is synchronized.
Trip Bypass - Breaker Failure		53	1	3	Struct			

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	Active	53	1	3	Bit	0x4 (3)	-	Signal: Active
	Pickup	53	1	3	Bit	0x80 (8)	-	Signal: BF-Module Started (Pickup)
	Trip (*)	53	1	3	Bit	0x100 (9)	-	Signal: Breaker Failure Trip
	Waiting for Trigger (*)	53	1	3	Bit	0x400 (11)	-	Waiting for Trigger
URTD		1007	1	3	Struct			
	WD1 Superv	1007	1	3	Bit	0x1 (1)	-	Signal: WD1, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)
	WD2 Superv	1007	1	3	Bit	0x2 (2)	-	Signal: WD2, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)
	WD3 Superv	1007	1	3	Bit	0x4 (3)	-	Signal: WD3, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)
	WD4 Superv	1007	1	3	Bit	0x8 (4)	-	Signal: WD4, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)
	WD5 Superv	1007	1	3	Bit	0x10 (5)	-	Signal: WD5, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)
	WD6 Superv	1007	1	3	Bit	0x20	-	Signal: WD6, Channel Supervision. The value "1" reports a detected channel

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
						(6)		failure. (The value "0" means that this RTD channel is healthy.)
	MB1 Superv	1007	1	3	Bit	0x40 (7)	-	Signal: MB1, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)
	MB2 Superv	1007	1	3	Bit	0x80 (8)	-	Signal: MB2, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)
	LB1 Superv	1007	1	3	Bit	0x100 (9)	-	Signal: LB1, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)
	LB2 Superv	1007	1	3	Bit	0x200 (10)	-	Signal: LB2, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)
	Aux1 Superv	1007	1	3	Bit	0x400 (11)	-	Signal: Aux1, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)
	Superv	1007	1	3	Bit	0x800 (12)	-	Signal: URTD Channel Supervision. The value "1" reports a detected channel failure of at least one channel. (The value "0" means that all RTD channels are healthy.)
	Aux2 Superv	1007	1	3	Bit	0x1000 (13)	-	Signal: Aux2, Channel Supervision. The value "1" reports a detected channel failure. (The value "0" means that this RTD channel is healthy.)

3.2 Measuring Values

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
37[1] - Underload	nTrips	21642	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
37[1] - Underload	nPickups	21648	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
37[2] - Underload	nTrips	21644	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
37[2] - Underload	nPickups	21650	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
46[1] - I.Unbalance	nRevTrips	21614	2	4	Float IEE754		-	Number of reverse spinning trips since last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
46[1] - I.Unbalance	nPickups	21724	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
46[1] - I.Unbalance	nTrips	21726	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
46[2] - I.Unbalance	nPickups	21730	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
46[2] - I.Unbalance	nTrips	21732	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
49 - Thermal Model	I2T Used	20482	2	4	Float IEE754		%	Thermal capacity used.
49 - Thermal Model	I2T Remained	20484	2	4	Float IEE754		%	Thermal capacity remained.

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
49 - Thermal Model	nAlarms	21658	2	4	Float IEE754		-	Number of alarms since the last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
49 - Thermal Model	nTrips	21660	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
50J[1] - Jam-Stall	nTrips	21580	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
50J[1] - Jam-Stall	nPickups	21662	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
50J[2] - Jam-Stall	nTrips	21582	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
50J[2] - Jam-Stall	nPickups	21664	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
50P[1] - Phase Inst. OC	nPickups	21666	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
50P[1] - Phase Inst. OC	nTrips	21668	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
50P[2] - Phase Inst. OC	nPickups	21670	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
50P[2] - Phase Inst. OC	nTrips	21672	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
50X[1] - Meas. Inst. OC	nPickups	21690	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
50X[1] - Meas. Inst. OC	nTrips	21692	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
50X[2] – Meas. Inst. OC	nPickups	21694	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
50X[2] – Meas. Inst. OC	nTrips	21696	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
CT	I0 Fund.	20114	2	4	Float IEE754		A	Measured value (calculated): Zero current (Fundamental)
CT	I1 Fund.	20116	2	4	Float IEE754		A	Measured value (calculated): Positive phase sequence current (Fundamental)
CT	I2 Fund.	20118	2	4	Float IEE754		A	Measured value (calculated): Unbalanced load current (Fundamental)
CT	Angle IX meas	20202	2	4	Float IEE754		°	Measured Value (Calculated): Angle of Phasor IX meas Reference phasor is required to calculate the angle. This is the first measured voltage (or current) channel with sufficiently high amplitude.
CT	Angle IA	20204	2	4	Float IEE754		°	Measured Value (Calculated): Angle of Phasor IA Reference phasor is required to calculate the angle. This is the first measured voltage (or current) channel with sufficiently high amplitude.
CT	Angle IB	20206	2	4	Float IEE754		°	Measured Value (Calculated): Angle of Phasor IB Reference phasor is required to calculate the angle. This is the first measured voltage (or current) channel with sufficiently high amplitude.
CT	Angle IC	20208	2	4	Float IEE754		°	Measured Value (Calculated): Angle of Phasor IC Reference phasor is required to calculate the angle. This is the first

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
								measured voltage (or current) channel with sufficiently high amplitude.
CT	IA THD	20210	2	4	Float IEE754		A	Measured Value (Calculated): IA Total Harmonic Current
CT	IB THD	20212	2	4	Float IEE754		A	Measured Value (Calculated): IB Total Harmonic Current
CT	IC THD	20214	2	4	Float IEE754		A	Measured Value (Calculated): IC Total Harmonic Current
CT	%IA THD	20216	2	4	Float IEE754		%	Measured Value (Calculated): IA Total Harmonic Distortion
CT	%IB THD	20218	2	4	Float IEE754		%	Measured Value (Calculated): IB Total Harmonic Distortion
CT	%IC THD	20220	2	4	Float IEE754		%	Measured Value (Calculated): IC Total Harmonic Distortion
CT	IA RMS	20316	2	4	Float IEE754		A	Measured value: Phase current (RMS)
CT	IB RMS	20318	2	4	Float IEE754		A	Measured value: Phase current (RMS)
CT	IC RMS	20320	2	4	Float IEE754		A	Measured value: Phase current (RMS)
CT	IX meas RMS	20322	2	4	Float IEE754		A	Measured value (measured): IX (RMS)
CT	%(I2/I1)	20376	2	4	Float IEE754		%	Measured value (calculated): I2/I1, phase sequence will be taken into account automatically.
CT	Angle I0	20378	2	4	Float IEE754		°	Measured Value (calculated): Angle of Zero Sequence System Reference phasor is required to calculate the angle. This is the first measured voltage (or current) channel with sufficiently high amplitude.
CT	Angle I1	20380	2	4	Float IEE754		°	Measured Value (calculated): Angle of Positive Sequence System

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
								Reference phasor is required to calculate the angle. This is the first measured voltage (or current) channel with sufficiently high amplitude.
CT	Angle I2	20382	2	4	Float IEE754		°	Measured value (calculated): Angle of Negative Sequence System Reference phasor is required to calculate the angle. This is the first measured voltage (or current) channel with sufficiently high amplitude.
Date and Time		20000	6	4	Struct			
	y	20000	6	4	Short	Word 0 (1)	-	Year
	m	20000	6	4	Short	Word 1 (17)	-	Month
	d	20000	6	4	Short	Word 2 (33)	-	Days
	h	20000	6	4	Short	Word 3 (49)	-	Hours
	min	20000	6	4	Short	Word 4 (65)	-	Minute
	ms	20000	6	4	Short	Word 5 (81)	-	Milliseconds
IRIG-B	Edges	20298	2	4	Float IEE754		-	Edges: Total number of rising and falling edges. This signal indicates if a signal is available at the IRIG-B input.

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
IRIG-B	NoOfFrameErrors	20300	2	4	Float IEE754		-	Total Number of Frame Errors. Physically corrupted Frame.
IRIG-B	NoOfFramesOK	20302	2	4	Float IEE754		-	Total number valid Frames.
MStart - Motor Start	ABK Rem.Time	20466	2	4	Float IEE754		s	This is the remaining anti-backspin time.
MStart - Motor Start	IA FLA	20468	2	4	Float IEE754		FLA	Measured value: Phase current multiples of FLA
MStart - Motor Start	IB FLA	20470	2	4	Float IEE754		FLA	Measured value: Phase current multiples of FLA
MStart - Motor Start	IC FLA	20472	2	4	Float IEE754		FLA	Measured value: Phase current multiples of FLA
MStart - Motor Start	NOCS Remaining	20474	2	4	Float IEE754		-	This counter shows the number of remaining permitted cold starts.
MStart - Motor Start	SPH Remaining	20476	2	4	Float IEE754		-	SPH Remaining
MStart - Motor Start	TBS Rem.Block.Time	20478	2	4	Float IEE754		s	In case that the Motor is blocked by TBS functions, the remaining blocking time is shown.
MStart - Motor Start	I3 PRMS avg	20510	2	4	Float IEE754		A	Average RMS current of all 3 phases
MStart - Motor Start	I3 PFLA avg	20512	2	4	Float IEE754		FLA	Average RMS current of all 3 phases as multiples of FLA
MStart - Motor Start	SPH Rem.Block.Time	20894	2	4	Float IEE754		min	In case that the Motor is blocked by an SPH blocking, the remaining blocking time is shown until the next motor start is permitted.
MStart - Motor Start	HighestRunI	21584	2	4	Float IEE754		A	Highest running phase current. The time stamp indicates the point in time when the maximum current has occurred. Resettable with »Sys . Res OperationsCr« or »Sys . Res All«.
MStart - Motor Start	HighestStartI	21586	2	4	Float IEE754		A	Highest starting phase current. The time stamp indicates the point in time when the maximum current has

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
								occured. Resettable with »Sys . Res OperationsCr« or »Sys . Res All«.
MStart - Motor Start	OCNT	21588	2	4	Float IEE754		-	Motor Operation count since last reset. Resettable with »Sys . Res OperationsCr« or »Sys . Res All«.
MStart - Motor Start	RunTime	21590	2	4	Float IEE754		h	Motor Operation time since last reset. Resettable with »Sys . Res OperationsCr« or »Sys . Res All«.
MStart - Motor Start	TOCS	21592	2	4	Float IEE754		-	Total Motor Operation count since last reset. Resettable with "Sys . Res TotalCr" or "All". Resettable with »Sys . Res TotalCr« or »Sys . Res All«.
MStart - Motor Start	TRunTime	21594	2	4	Float IEE754		h	Motor Operation (Motor run time) time since last reset. Resettable with »Sys . Res TotalCr« or »Sys . Res All«.
MStart - Motor Start	nEmrgOvr	21596	2	4	Float IEE754		-	Number of emergency overrides since last reset. Resettable with »Sys . Res OperationsCr« or »Sys . Res All«.
MStart - Motor Start	nInSqTrips	21598	2	4	Float IEE754		-	Number of incomplete sequence trips since last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
MStart - Motor Start	nTRNTrips	21606	2	4	Float IEE754		-	Number of transition trips since last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
MStart - Motor Start	nZSWTrips	21608	2	4	Float IEE754		-	Number of zero speed switch trips since last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
MStart - Motor Start	nSPHBlocks	21654	2	4	Float IEE754		-	Number of start per hour blocks since last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
MStart - Motor Start	nTBSBlocks	21656	2	4	Float IEE754		-	Number of time between start blocks since last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
MStart - Motor Start	Highest%I2/I1	21722	2	4	Float IEE754		%	Highest %I2/I1 value since last reset. The time stamp indicates the point in time when the maximum unbalanced

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
								load has occurred. Resettable with »Sys . Res OperationsCr« or »Sys . Res All«.
Modbus	Mapped Meas 1	23000	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 2	23002	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 3	23004	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 4	23006	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 5	23008	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 6	23010	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 7	23012	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 8	23014	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 9	23016	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 10	23018	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 11	23020	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.

Module (ANSI / IEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
Modbus	Mapped Meas 12	23022	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 13	23024	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 14	23026	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 15	23028	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
Modbus	Mapped Meas 16	23030	2	4	Float IEE754		-	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.
RTD	Hottest WD	20504	2	4	Float IEE754		°C	The actual value for the hottest winding temperature.
RTD	Hottest MB	20506	2	4	Float IEE754		°C	The actual value for the hottest motor bearing temperature.
RTD	Hottest LB	20508	2	4	Float IEE754		°C	The actual value for the hottest load bearing temperature.
RTD	HighestLbTemp	21618	2	4	Float IEE754		°C	Highest load bearing temperature since the last reset. Resettable via »Sys . Res OperationsCr« oder »Sys . Res All«.
RTD	HighestMbTemp	21620	2	4	Float IEE754		°C	Highest motor bearing temperature since the last reset. Resettable via »Sys . Res OperationsCr« oder »Sys . Res All«.
RTD	HighestWdTemp	21622	2	4	Float IEE754		°C	Highest motor winding temperature since the last reset. Resettable via »Sys . Res OperationsCr« oder »Sys . Res All«.
RTD	nAuxAlarms	21624	2	4	Float IEE754		-	Number of auxiliary temperature alarms since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
RTD	nAuxTrips	21626	2	4	Float IEE754		-	Number of auxiliary temperature trips since last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
RTD	nChannelFails	21628	2	4	Float IEE754		-	Number of RTD channel failures. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
RTD	nLbAlarms	21630	2	4	Float IEE754		-	Number of load bearing temperature alarms since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
RTD	nLbTrips	21632	2	4	Float IEE754		-	Number of load bearing temperature trips since last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
RTD	nMbAlarms	21634	2	4	Float IEE754		-	Number of motor bearing temperature alarms since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
RTD	nMbTrips	21636	2	4	Float IEE754		-	Number of motor bearing temperature trips since last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
RTD	nWdAlarms	21638	2	4	Float IEE754		-	Number of winding temperature alarms since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.
RTD	nWdTrips	21640	2	4	Float IEE754		-	Number of winding temperature trips since last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
RTD	Hottest Aux	21820	2	4	Float IEE754		°C	The actual value for the hottest Auxiliary temperature.
RTD	HighestAuxTemp	21822	2	4	Float IEE754		°C	Highest Auxiliary temperature since the last reset. Resettable via »Sys . Res OperationsCr« oder »Sys . Res All«.
Remote Trip	nPickups	24058	2	4	Float IEE754		-	Number of pickups since last reset. Resettable with »Sys . Res AlarmCr« or »Sys . Res All«.

Module (ANSI / IEC)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
Remote Trip	nTrips	24060	2	4	Float IEE754		-	Number of trips since the last reset. Resettable with »Sys . Res TripCr« or »Sys . Res All«.
URTD	Aux2	20328	2	4	Float IEE754		°C	Auxiliary2
URTD	WD1	20330	2	4	Float IEE754		°C	Winding 1
URTD	WD2	20332	2	4	Float IEE754		°C	Winding 2
URTD	WD3	20334	2	4	Float IEE754		°C	Winding 3
URTD	WD4	20336	2	4	Float IEE754		°C	Winding 4
URTD	WD5	20338	2	4	Float IEE754		°C	Winding 5
URTD	WD6	20340	2	4	Float IEE754		°C	Winding 6
URTD	MB1	20342	2	4	Float IEE754		°C	Motor Bearing 1
URTD	MB2	20344	2	4	Float IEE754		°C	Motor Bearing 2
URTD	LB1	20346	2	4	Float IEE754		°C	Load Bearing 1
URTD	LB2	20348	2	4	Float IEE754		°C	Load Bearing 2
URTD	Aux1	20350	2	4	Float IEE754		°C	Auxiliary1
URTD	RTD Max	20486	2	4	Float IEE754		°C	Maximum temperature of all channels.
Values	Build	20008	2	4	Float IEE754		-	Build Number
Values	Operating hours Cr	20010	2	4	Float IEE754		h	Operating hours counter of the protective device

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
Values	Hours Counter	20514	2	4	Float IEE754		h	Resettable device operation hours counter. Resettable with »Sys . Res TotalCr« or »Sys . Res All«.

3.3 Commands

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
Acknowledge	LEDs	22000	1	5	0xFF00		-	LEDs
Acknowledge	Relay Outputs	22001	1	5	0xFF00		-	Relay Outputs
Acknowledge	SCADA	22002	1	5	0xFF00		-	SCADA Communication
Acknowledge	Device	22003	1	5	0xFF00		-	Device
Acknowledge	Ack TripCmd	22005	1	5	0xFF00		-	Signal: Acknowledge Trip Command
Reset	Modbus diagnosis counter	22006	1	5	0xFF00		-	Modbus diagnosis counter
Comm Cmd	Assbl Comm Cmd 1	22020	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 2	22021	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 3	22022	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 4	22023	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 5	22024	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 6	22025	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 7	22026	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 8	22027	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 9	22028	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 10	22029	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
Comm Cmd	Assbl Comm Cmd 11	22030	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 12	22031	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 13	22032	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 14	22033	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 15	22034	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Comm Cmd	Assbl Comm Cmd 16	22035	1	5	0xFF00=On, 0x0000=Off		-	Assignable Communication Command
Fault rec	Res all rec	22040	1	5	0xFF00		-	Reset all records
PSet-Switch	Comm PS1	22050	1	5	0xFF00		-	Communication Setting Group1
PSet-Switch	Comm PS2	22051	1	5	0xFF00		-	Communication Setting Group2
PSet-Switch	Comm PS3	22052	1	5	0xFF00		-	Communication Setting Group3
PSet-Switch	Comm PS4	22053	1	5	0xFF00		-	Communication Setting Group4
Maint Mode	Maint Mode Comm	22054	1	5	0xFF00=On, 0x0000=Off		-	Signal: Arc Flash Reduction Maintenance Comm Mode
Res I2T Used	Res I2T Used	22055	1	5	0xFF00		-	Reset thermal capacity used.
Res OperationsCr	Res OperationsCr	22056	1	5	0xFF00		-	Reset all counters in history group operations
Res AlarmCr	Res AlarmCr	22057	1	5	0xFF00		-	Reset all counters in history group alarms
Res TripCr	Res TripCr	22058	1	5	0xFF00		-	Reset all counters in history group trips
Res TotalCr	Res TotalCr	22059	1	5	0xFF00		-	Reset all counters in history group total
Res All	Res All	22060	1	5	0xFF00		-	Reset of all Counters

3.4 Settings

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
Date and Time		32500	6	3 16	Struct			
	y	32500	6	3 16	Short	Word 0 (1)	-	Year
	m	32500	6	3 16	Short	Word 1 (17)	-	Month
	d	32500	6	3 16	Short	Word 2 (33)	-	Days
	h	32500	6	3 16	Short	Word 3 (49)	-	Hours
	min	32500	6	3 16	Short	Word 4 (65)	-	Minute
	ms	32500	6	3 16	Short	Word 5 (81)	-	Milliseconds
Fault rec		50000	9	3 16	Struct			
	RecordNo	50000	9	3 16	Short	Word 0 (1)	-	Record Number
	Trip Cause	50000	9	3 16	Short	Word 1 (17)	-	Code for the trip cause. In case of several simultaneous trip causes the primary cause is selected. If there is another trip later then the new trip cause overwrites the previous one. The codes for the trip cause are documented in the SCADA documentation.

Module (ANSI / IEEE)	Name Function	Start Register Address	No. of Modbus Registers	Function code	Format	Bit Mask (Bit position)	Unit	Description
	Pickup Cause	50000	9	3 16	Short	Word 2 (33)	-	Code for last Pickup cause corresponds to fault record: See scada doc for correlation between pickup reason and code
	Fault No.	50000	9	3 16	Short	Word 3 (49)	-	Waveform number
	No of Grid Faults	50000	9	3 16	Short	Word 4 (65)	-	Number of grid faults: This is a counter for all faults (i.e. General Pickups »Prot . Pickup«), but except faults during a running cycle of the Automatic Reclosure module (signal »AR . Running«). (Remark: The »Fault No.« counts every new fault independent of AR cycles. This means that for protective devices without AR module these two counters are equivalent.)
	Time stamp:	50000	9	3 16	long long	Word 5- Word 8 (81)	-	Timestamp in milliseconds since 1970

3.5 Cause of Trip

Cause of trip reason is provided on two different Modbus addresses:

- At address 5004 the “last primary trip cause” is available. This means, in case of several simultaneous trip causes the primary cause is selected. If there is another trip later then the new trip cause overwrites the previous one. The trip cause can be read as long as a trip reason is present. In addition, the content of this register can be latched. The trip cause is latched in the same way as other trip signals, that means if the corresponding latching setting in Modbus is active, the content of the register is fixed until it is acknowledged by command.
- At address 50000 and up the last trip and alarm reason is available with related record, fault, net number and time stamp. Any saved record can be requested by sending the record number to the corresponding register. Be aware that the content of these registers can only be read entirely and that the content changes every time a new fault occurs in the fault recorder.

All required fault values must be defined within a SCADApter (ErSMap) mapping file. The default datapoint list cannot be used in this case. All data-points that are needed for communicating with the substation must be defined as a ErSMap mapping file. (See also the separate SCADApter User Manual.)

If not a specific fault is selected, last fault value is presented on these addresses.

The following table is showing the “trip cause code” and its relation to the “trip cause reason”.

Trip Cause	Description	Module
0	?	37[1], 37[2], 49, 50J[1], 50J[2], MLS, RTD
1	NORM	
2	EXTERNAL	Ex87, Remote Trip
3	PH IOC	50P[1], 50P[2]
4	IG IOC	50X[1], 50X[2]
17	I UNBAL	46[1], 46[2]

3.6 Fast Status Register

At registers ≥ 5000 an area is provided where common status indicator bits can be read from one location. See the Register Maps for information that is available in general.

At registers 5002 and 5003 the user has the option to collect arbitrary device status information. The purpose is to get a custom set of device states in a single request. Some of these positions are already pre-configured.

The following table lists the pre-configured states:

General Function	Bit Position	Short Description	Long Description
Relay Health	0	Health status	
General Trips / General Pickups	1	Pickup	General pickup of any type - not element-specific.
	2	Trip	General Trip of any type - not element-specific.
	3		
	4		
	5		
	6		
	7		
Breaker [*]	8	Pos Open	Breaker is in Open position.
	9	Pos Close	Breaker is in Closed position.
	10	Pickup	Breaker failure detected and timer in progress.
	11	Trip	Breaker failure detected and trip initiated.
	12	Lockout	Breaker failure lockout.
	13		
	14		
	15		

General Function	Bit Position	Short Description	Long Description
Sgen status	16	Running	Test simulation signal generation "Running".
ARMS [**]	17	Maintenance	Maintenance mode active.
Motor [***]	18	Motor Relay Ready - (stopped)	
	19	Motor Relay Start	
	20	Motor Relay Running	

[*] Only available in devices with Breaker Control.

[]** Only available in devices that support Maintenance mode.

[*]** Only available in Motor Relays.

Modbus Datapoints IL026011EN

Effective 2023-05-17

EMR-3MPO

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